

# Nutmeg: a MIP and CP Hybrid Solver Using Branch-and-Check

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Decomposition at 70: In Honor of Jacques Desrosieres and His Legacy

11 February 2021



# Overview

- A generic method to find combinatorial Benders cuts.
- Based logic-based Benders decomposition.
  - Generalizes classical Benders decomposition to discrete subproblems.
  - No specific form of cuts due to its generality. User must derive cuts valid for their problem.
  - Otherwise, naive combinatorial Benders cuts:  $x_1, \dots, x_n$  binary,  $x_1 + x_2 + \dots + x_n \leq n - 1$
- Uses propagation (aka inference) and conflict analysis (aka conflict-driven clause learning) from constraint programming and Boolean satisfiability (SAT).
- Central idea: find a set of values to some master-problem variables that implicate infeasibility in the subproblem.

# Example

## Vehicle Routing Problem with Time Windows

- Familiar problem to illustrate the method.
- Obviously not the best way to solve the VRPTW.
- Master problem has arc variables and network flow constraints.
- Travel time and time window constraints moved into the Benders subproblem.
- Ignore load in this example.

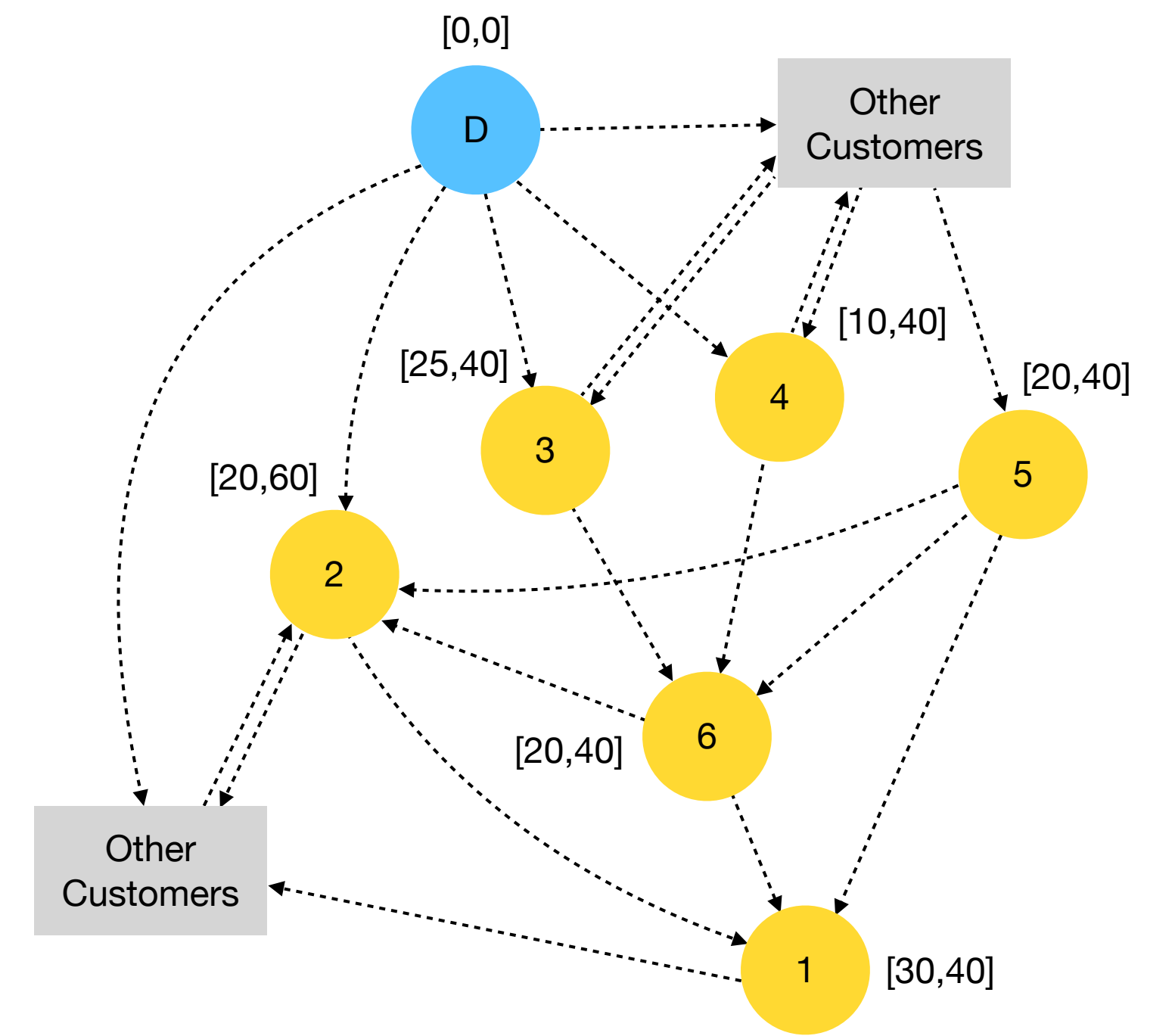
# Implication Graph

$t_i$ : earliest time of starting service at vertex  $i$

$c_{i,j}$ : cost/travel time from  $i$  to  $j$



# Network



# Branch-and-Bound Tree

# Implication Graph

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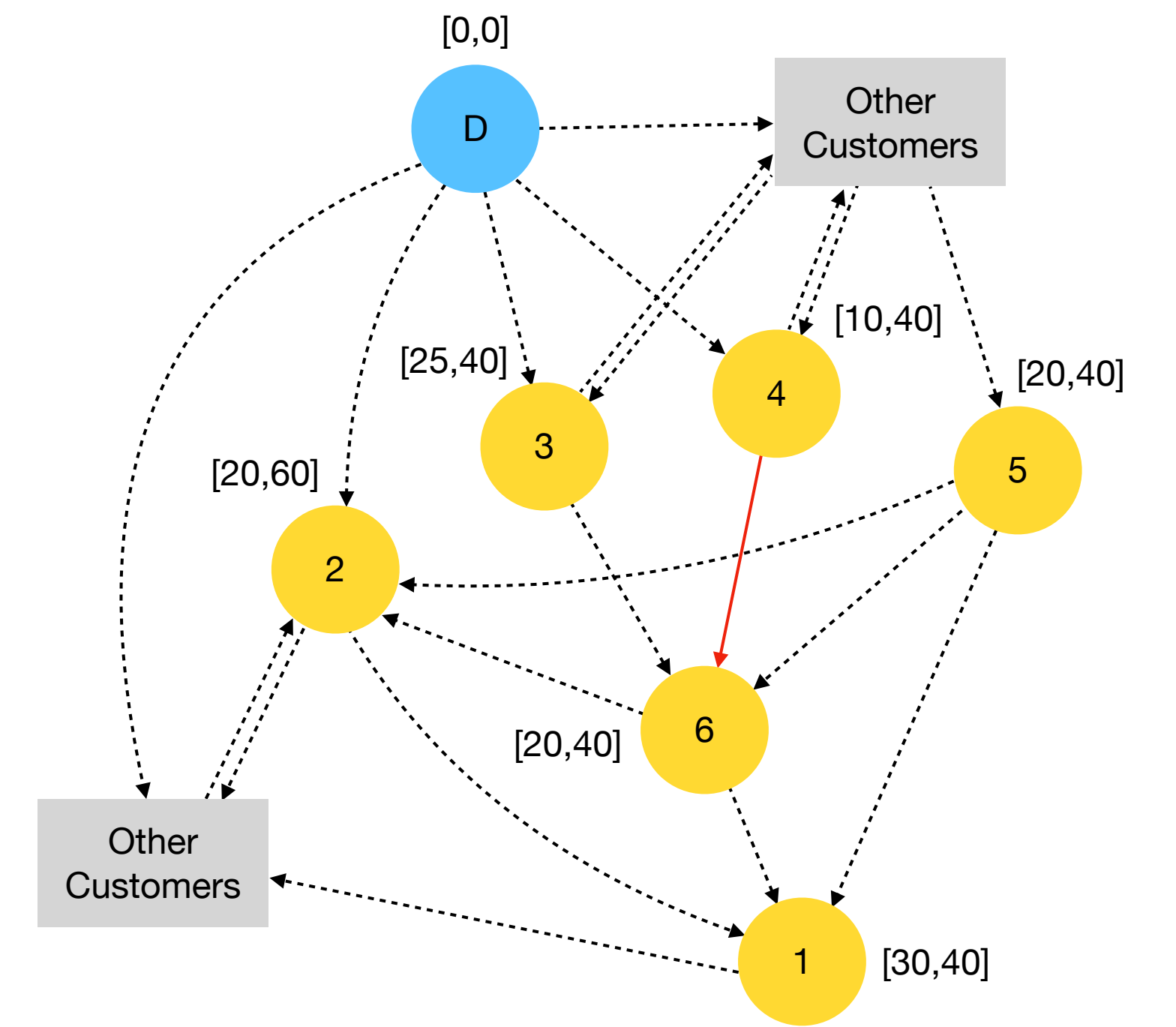
Data

Decision (branching)

Propagation (inferred)

$$x_{4,6} = 0$$

# Network



# Branch-and-Bound Tree

$$x_{4,6} = 0$$

## Implication Graph

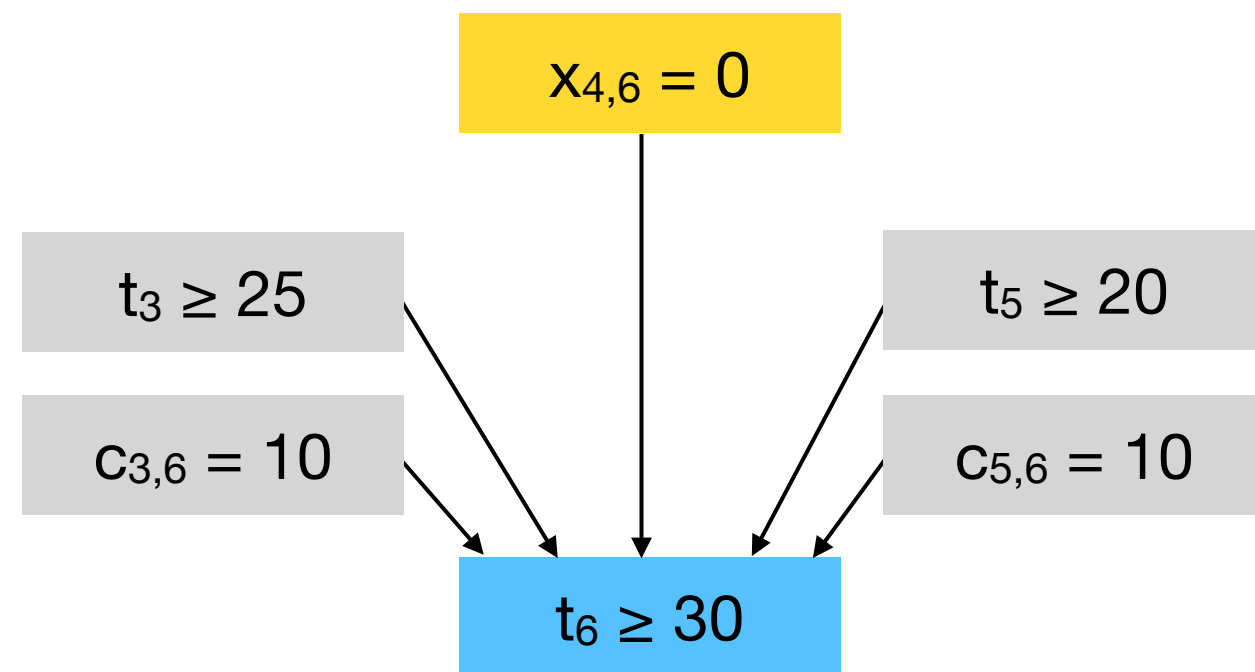
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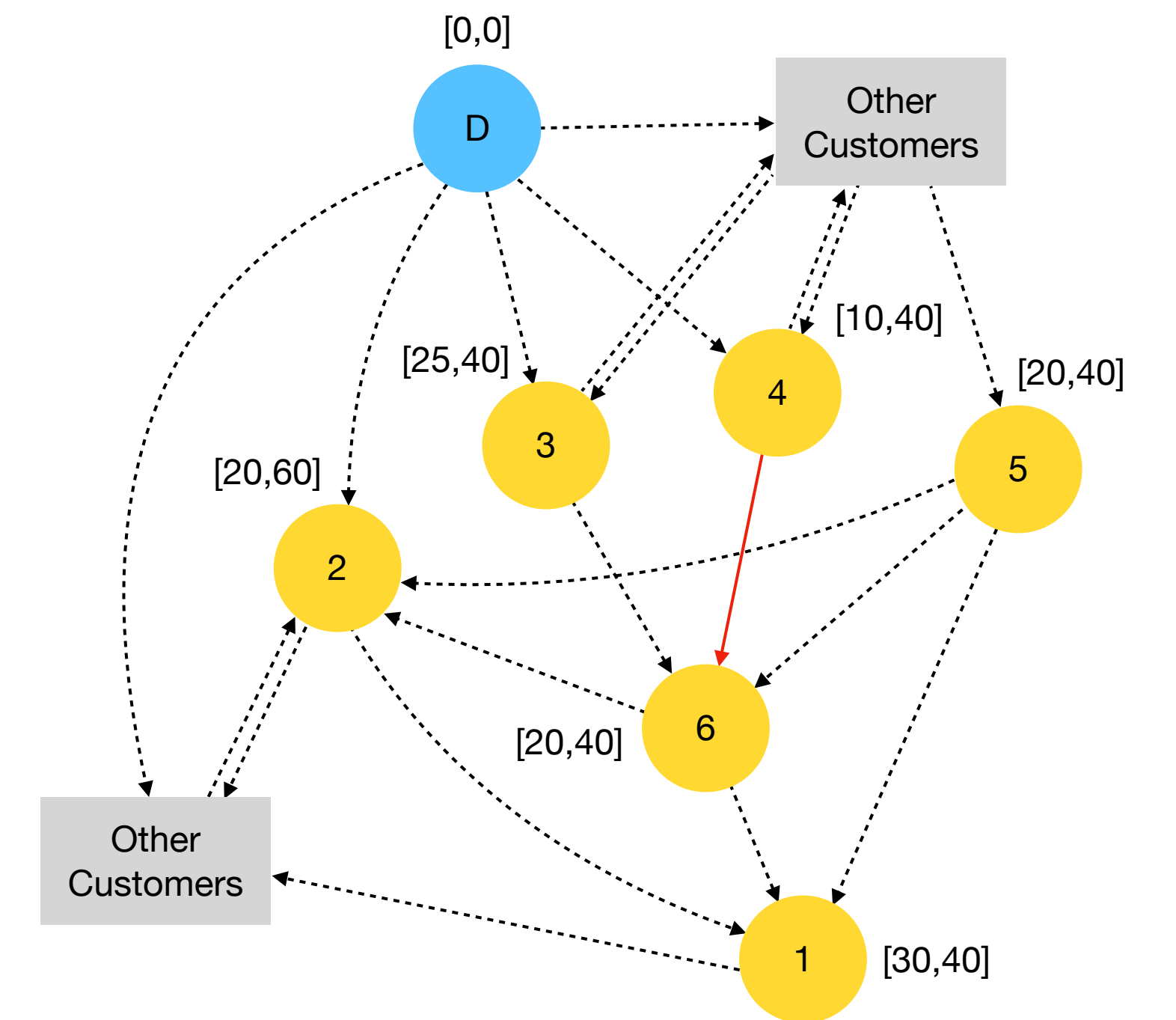
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## Network



## Branch-and-Bound Tree

$x_{4,6} = 0$

## Implication Graph

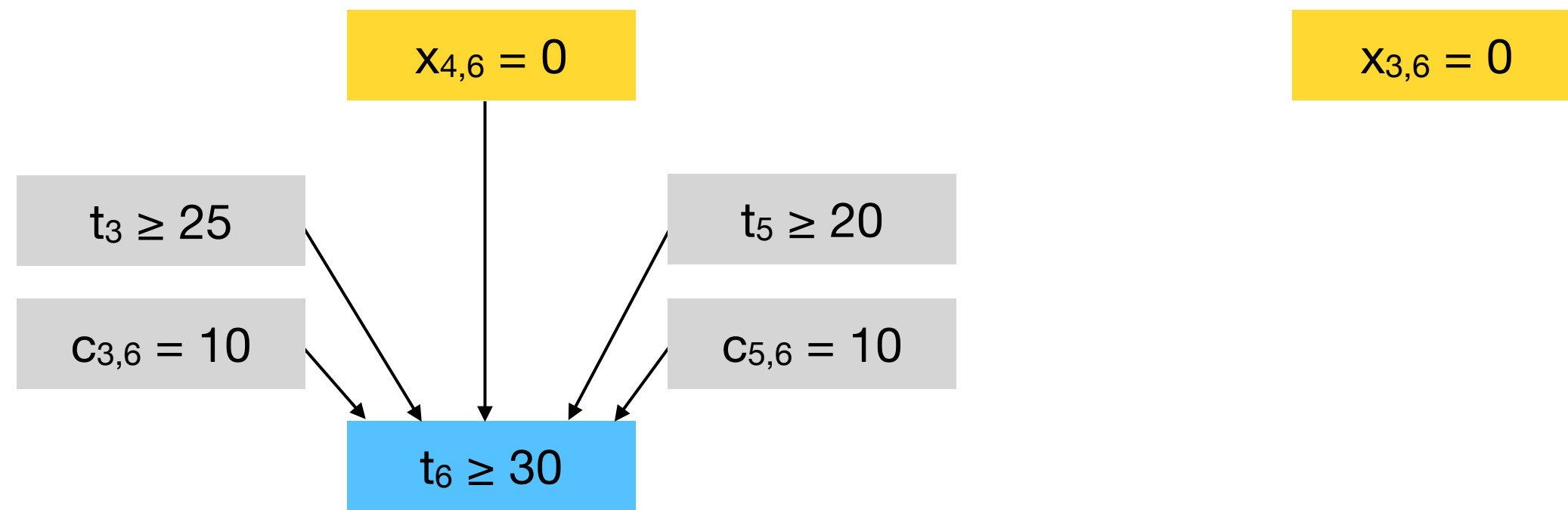
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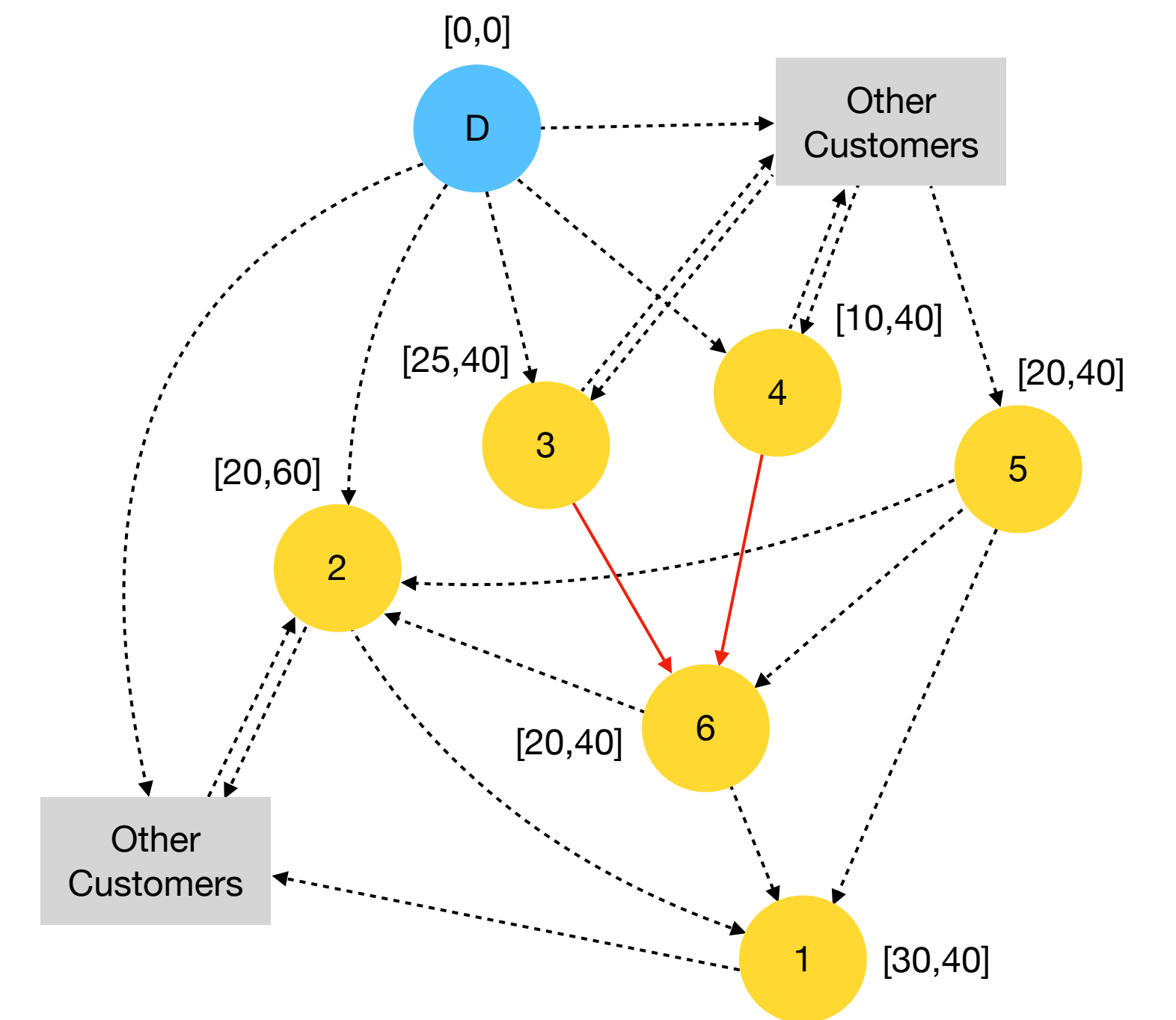
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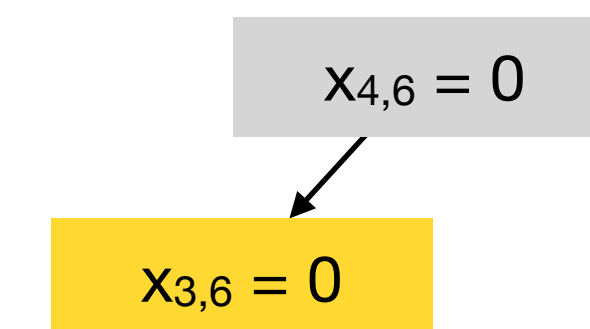
Propagation (inferred)



## Network



## Branch-and-Bound Tree



## Implication Graph

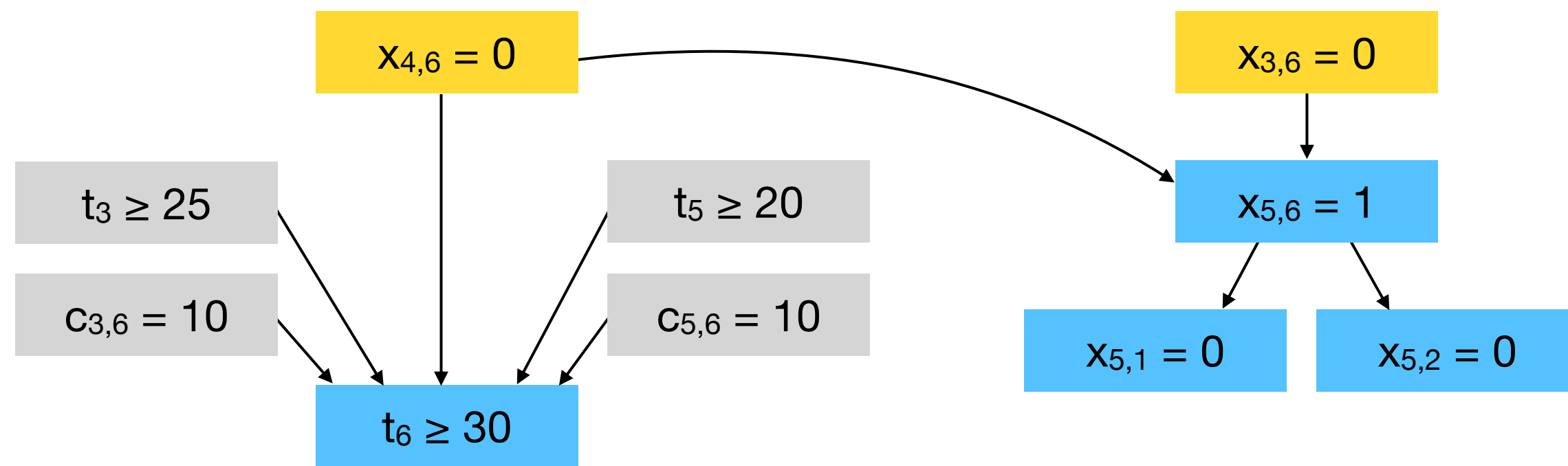
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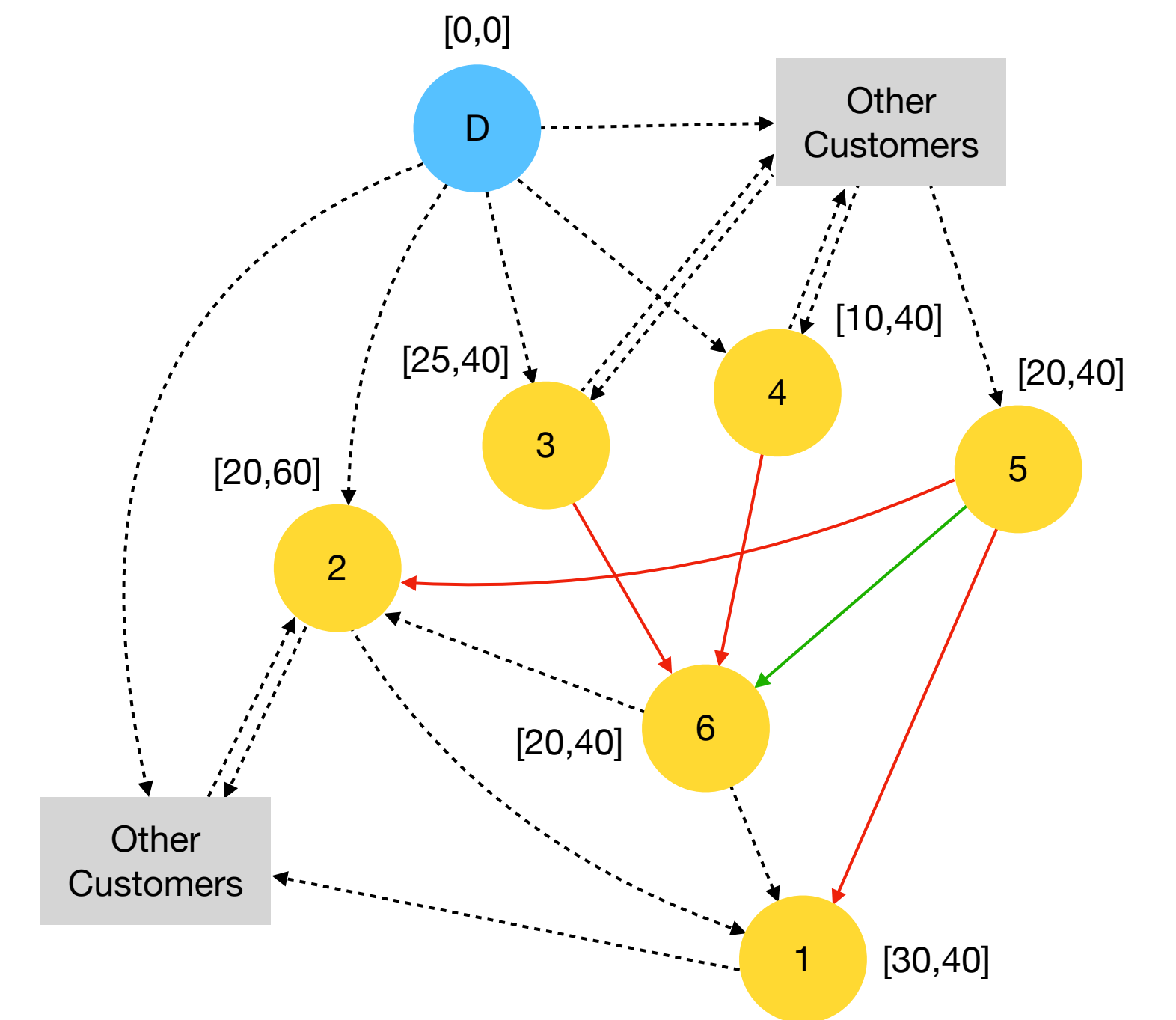
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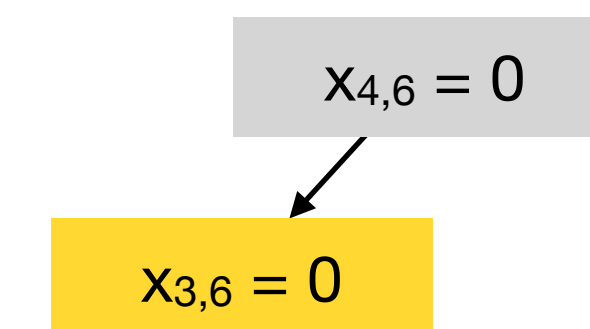
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## Network



## Branch-and-Bound Tree





## Implication Graph

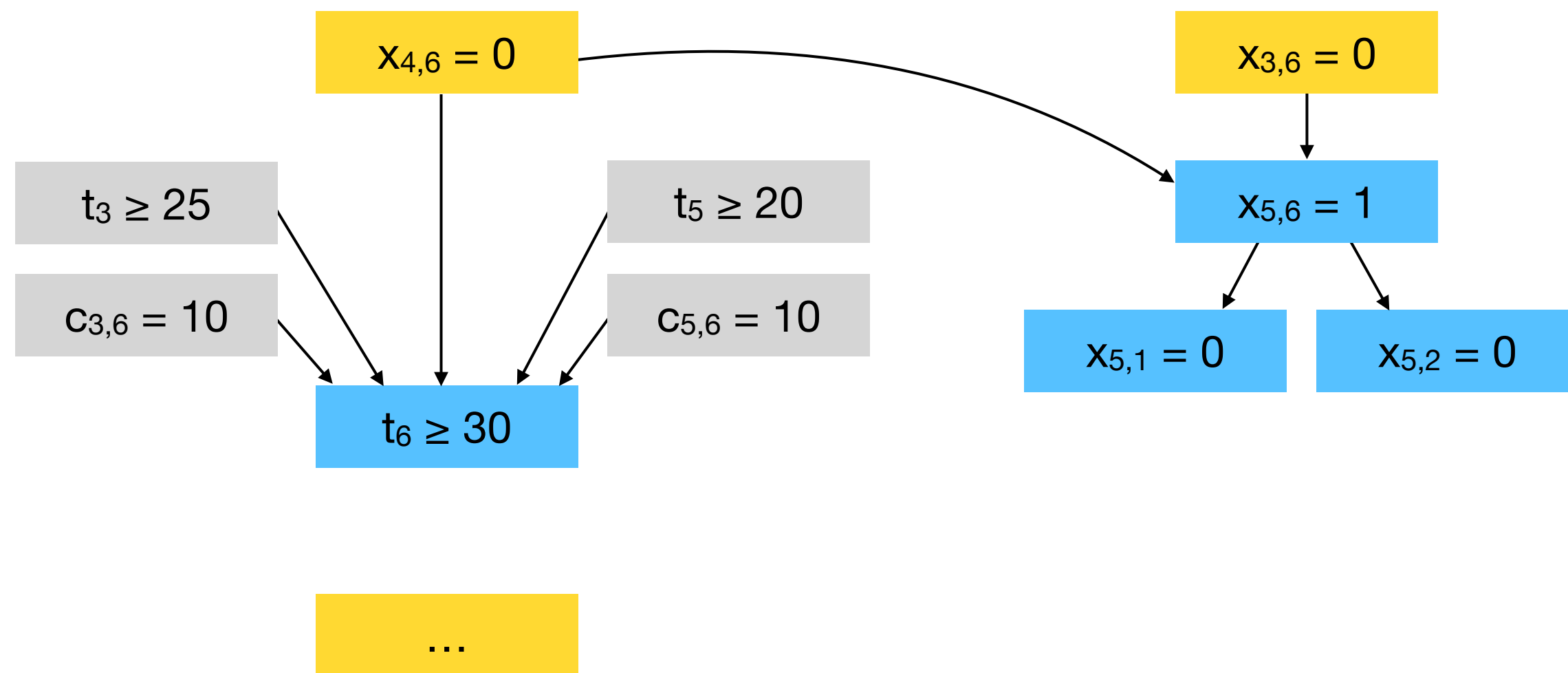
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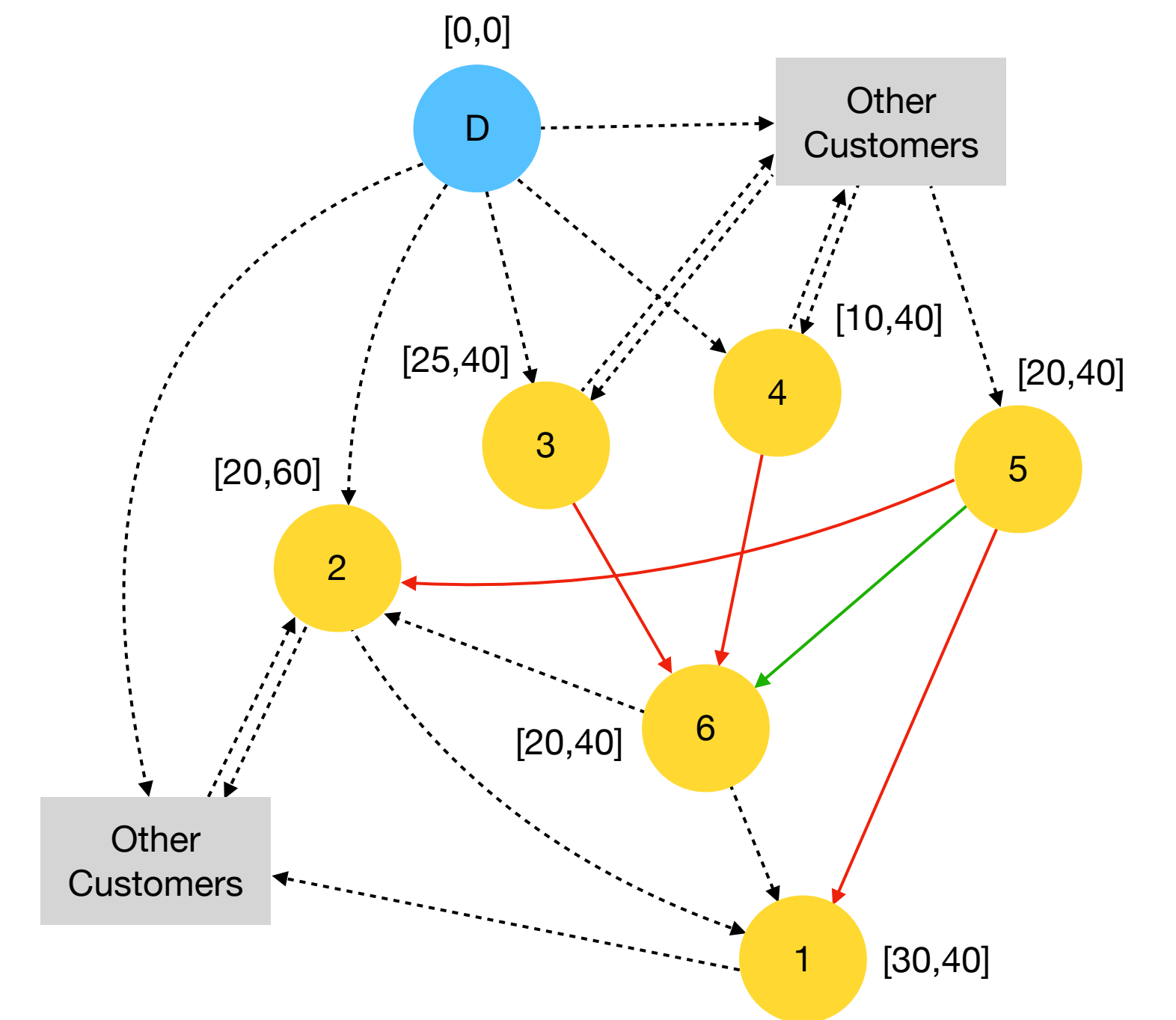
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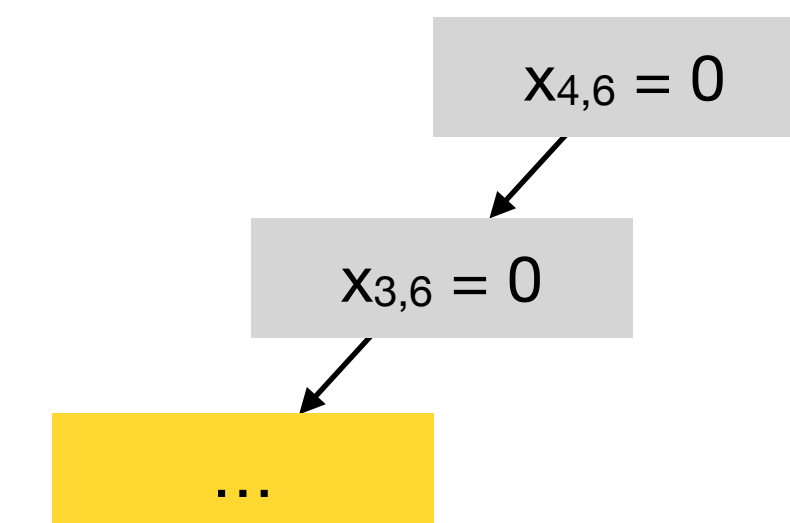
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## Network



## Branch-and-Bound Tree



## Implication Graph

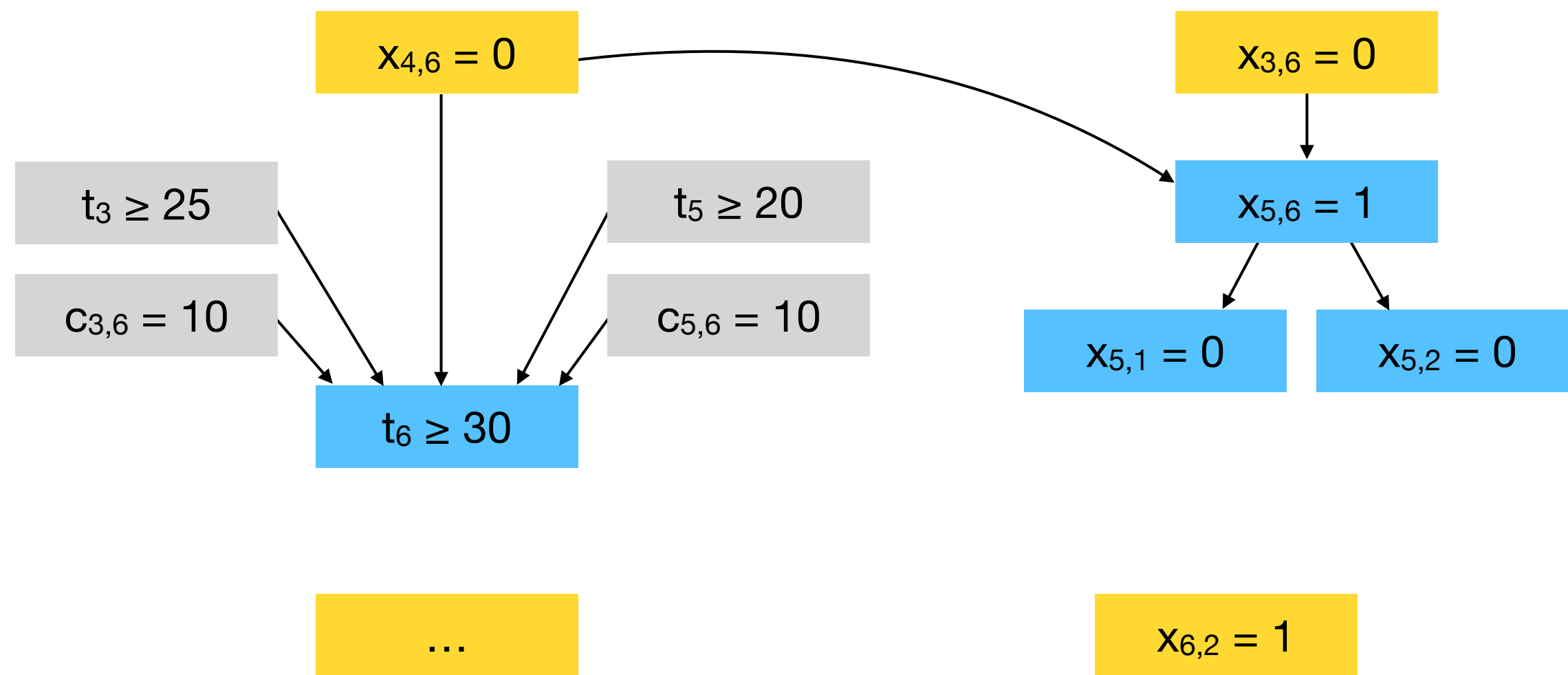
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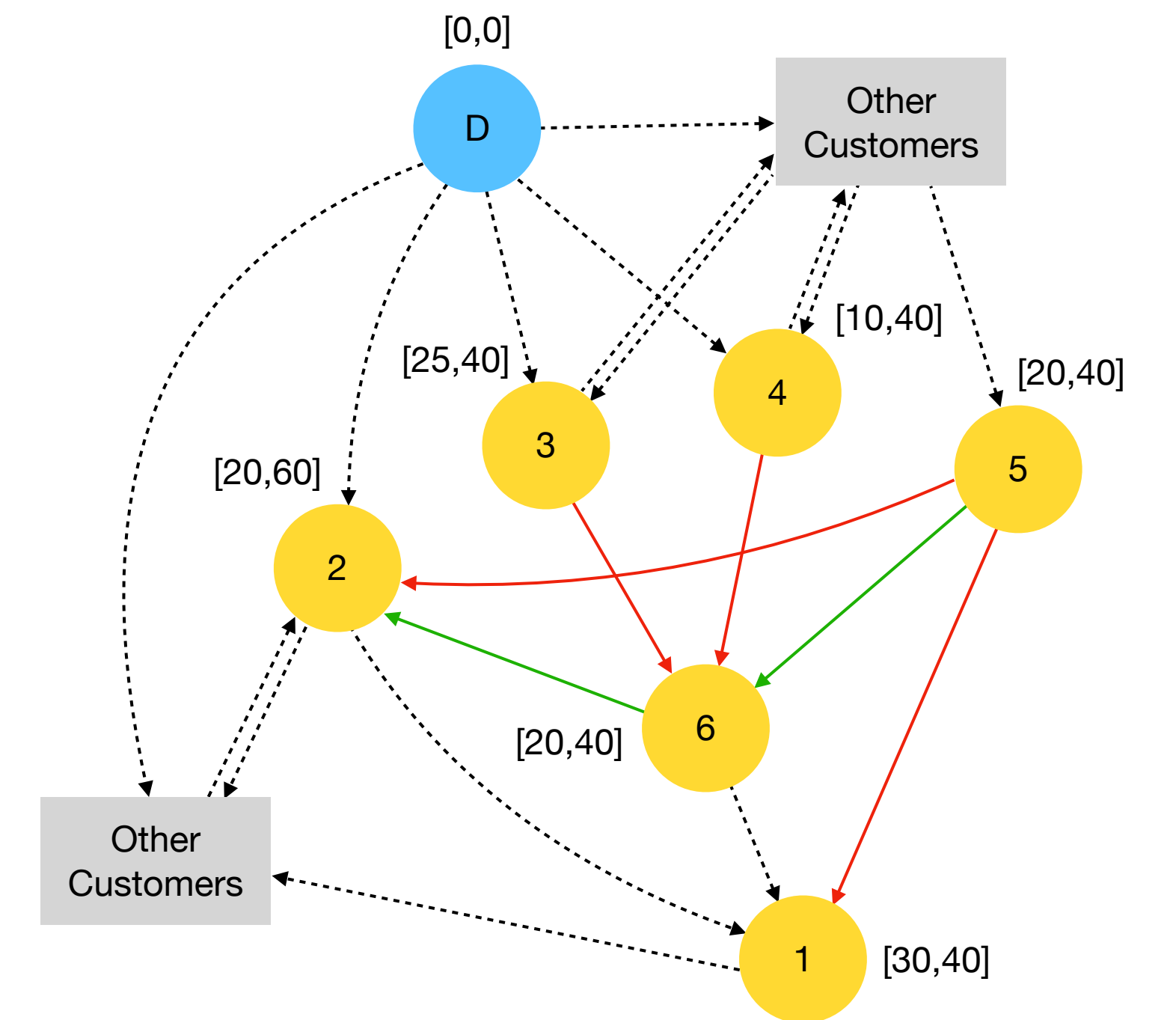
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Decision (branching)

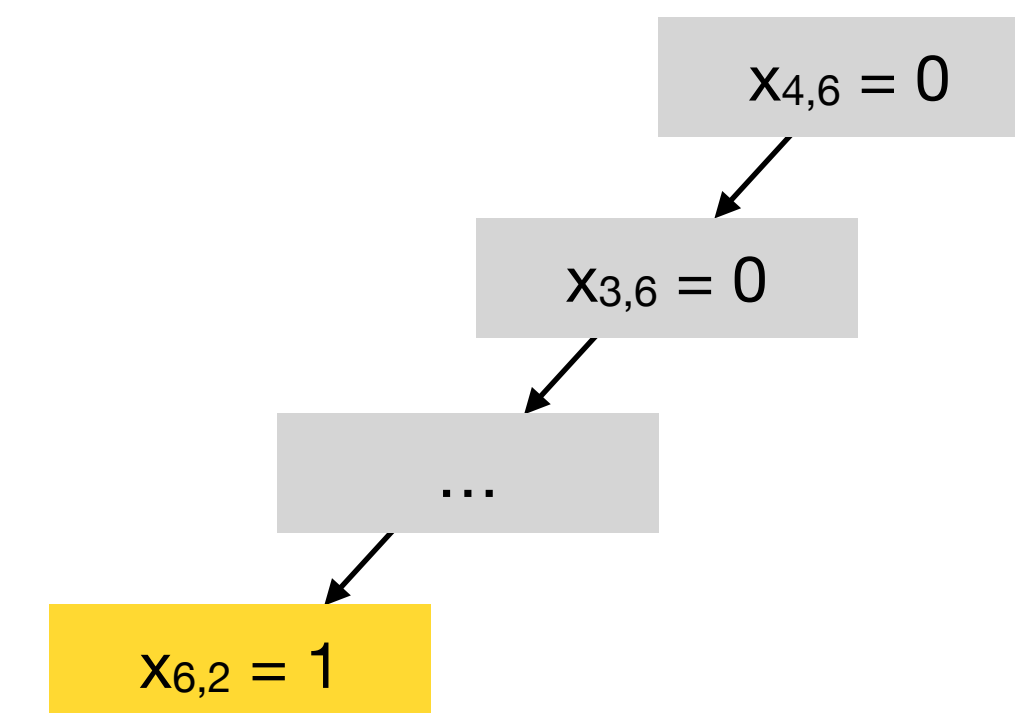
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## Network



## Branch-and-Bound Tree



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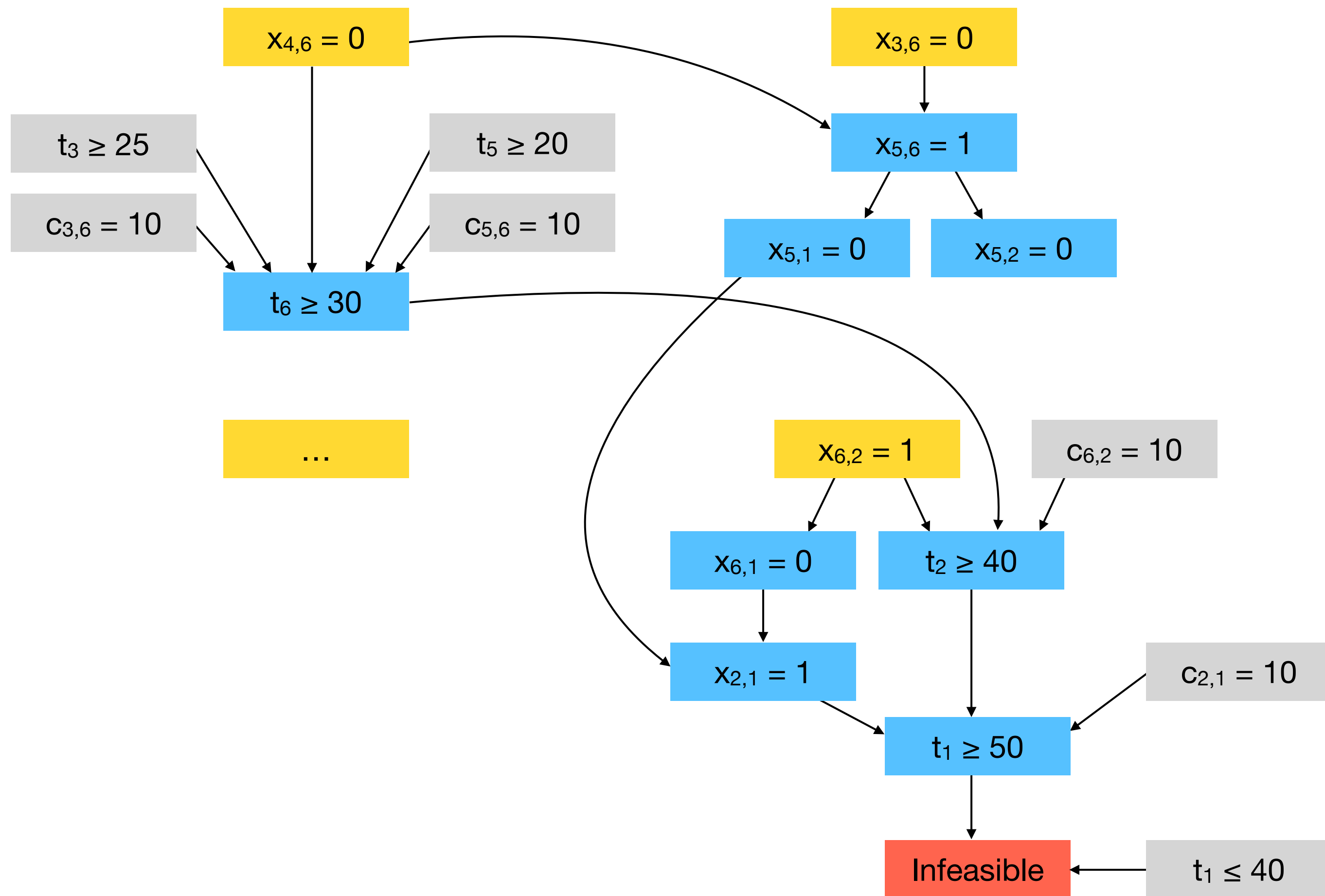
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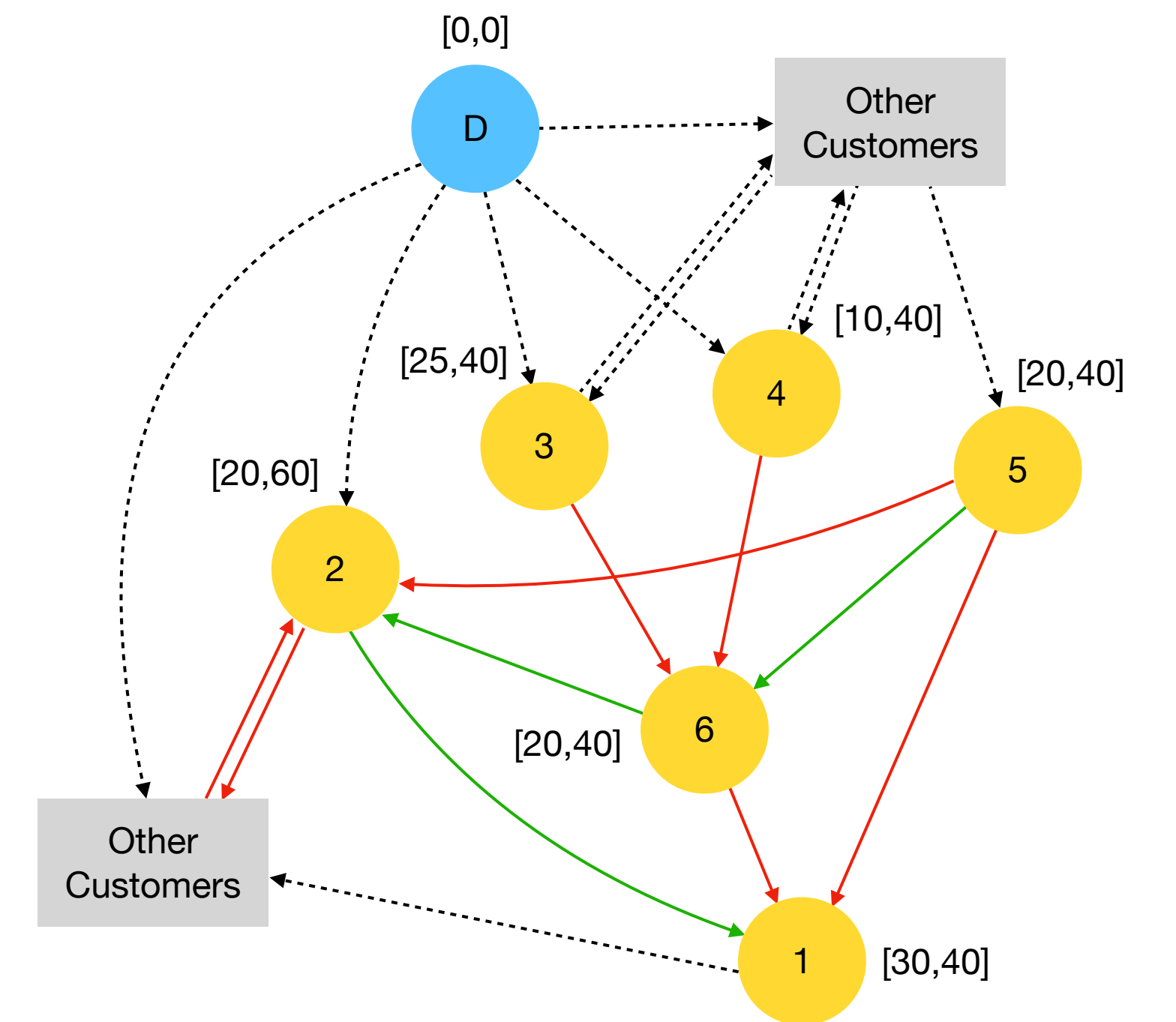
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Decision (branching)

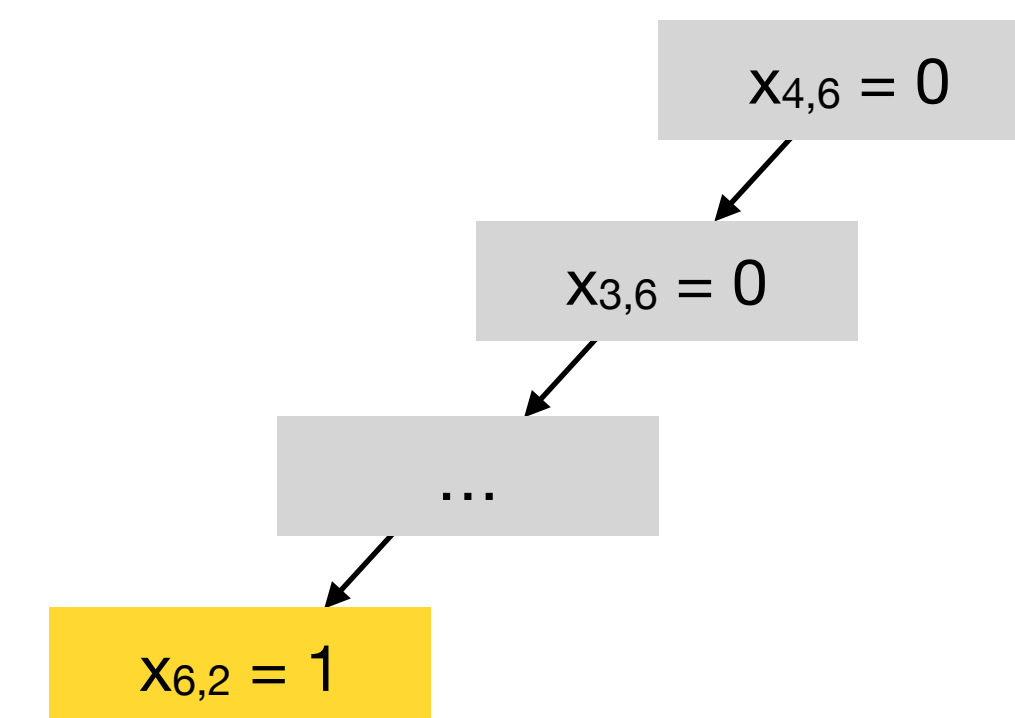
Propagation (inferred)



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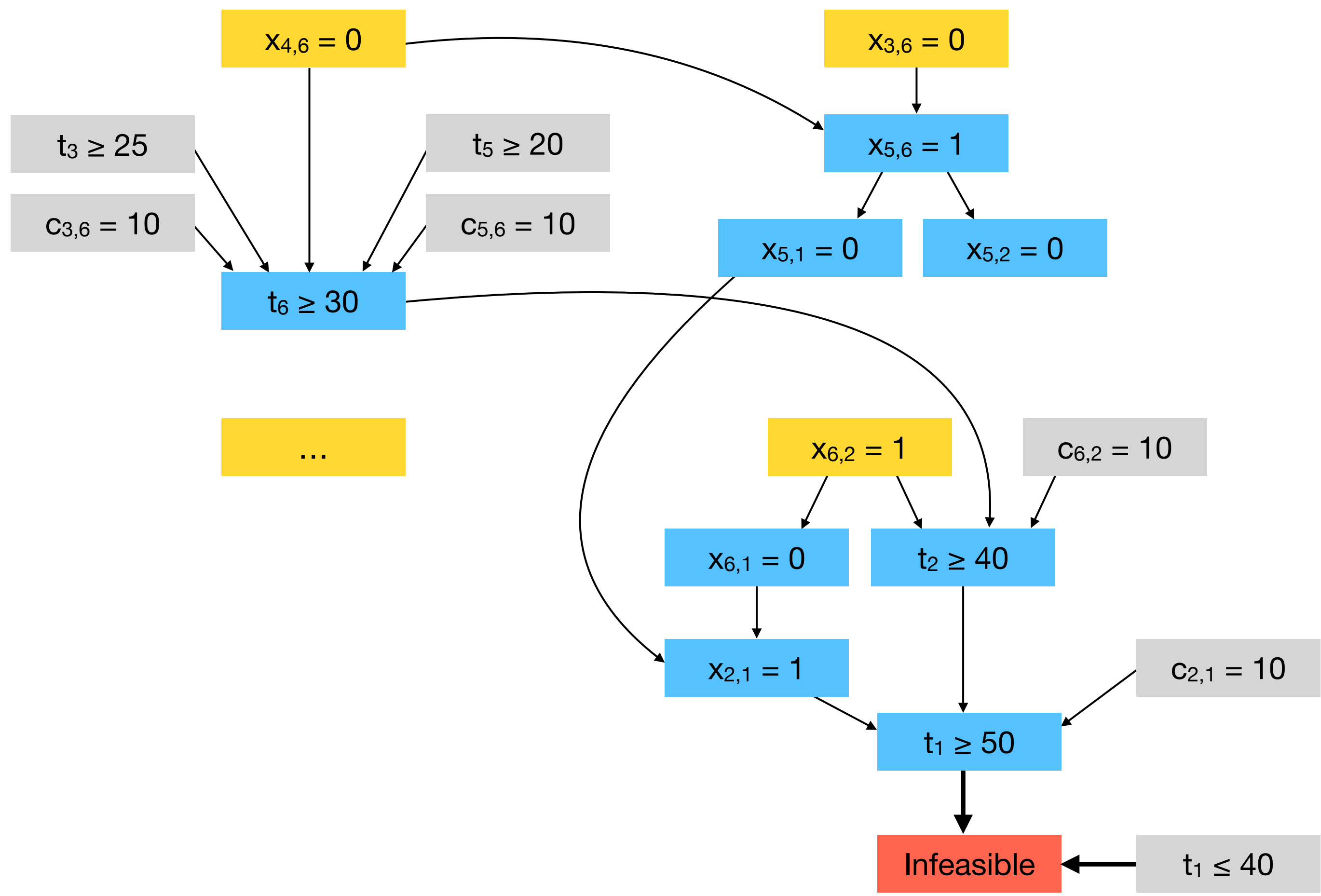


## Branch-and-Bound Tree

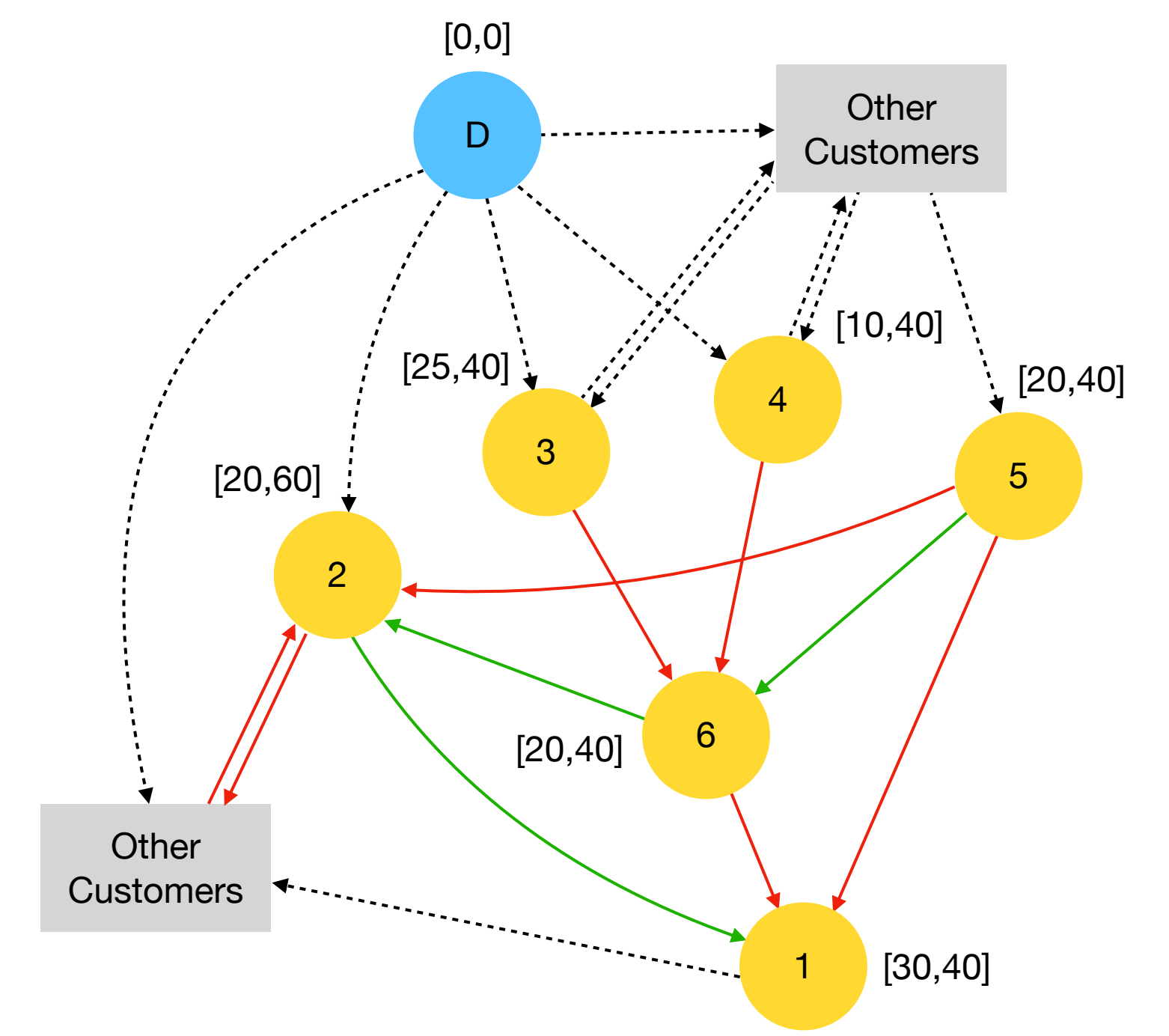


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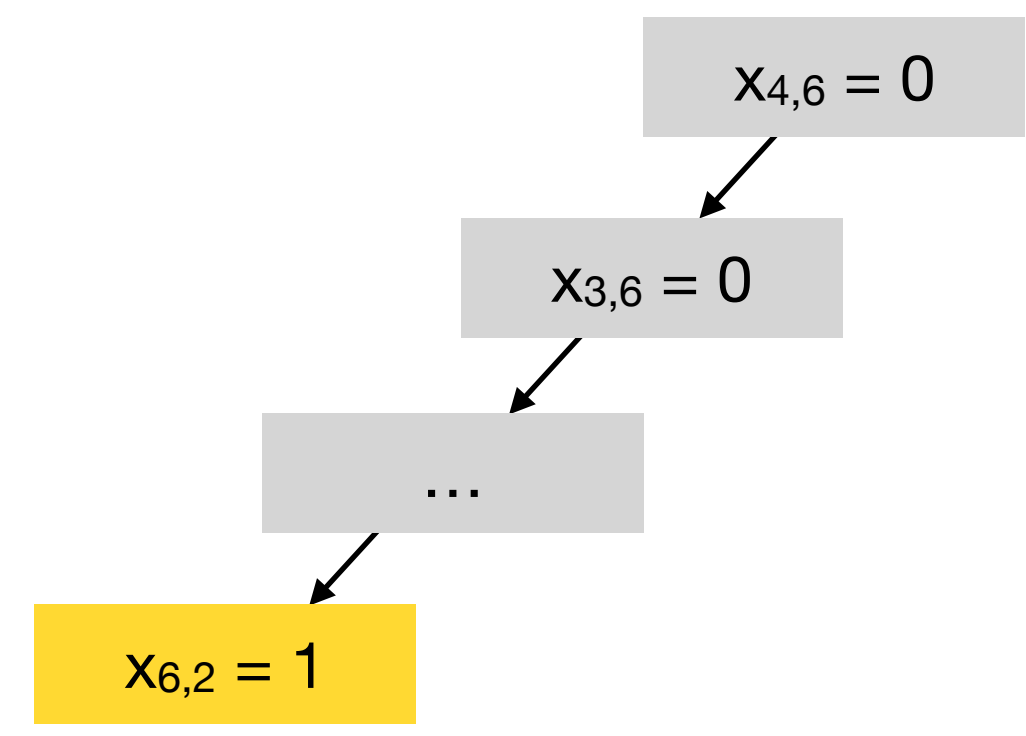
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# Branch-and-Bound Tree



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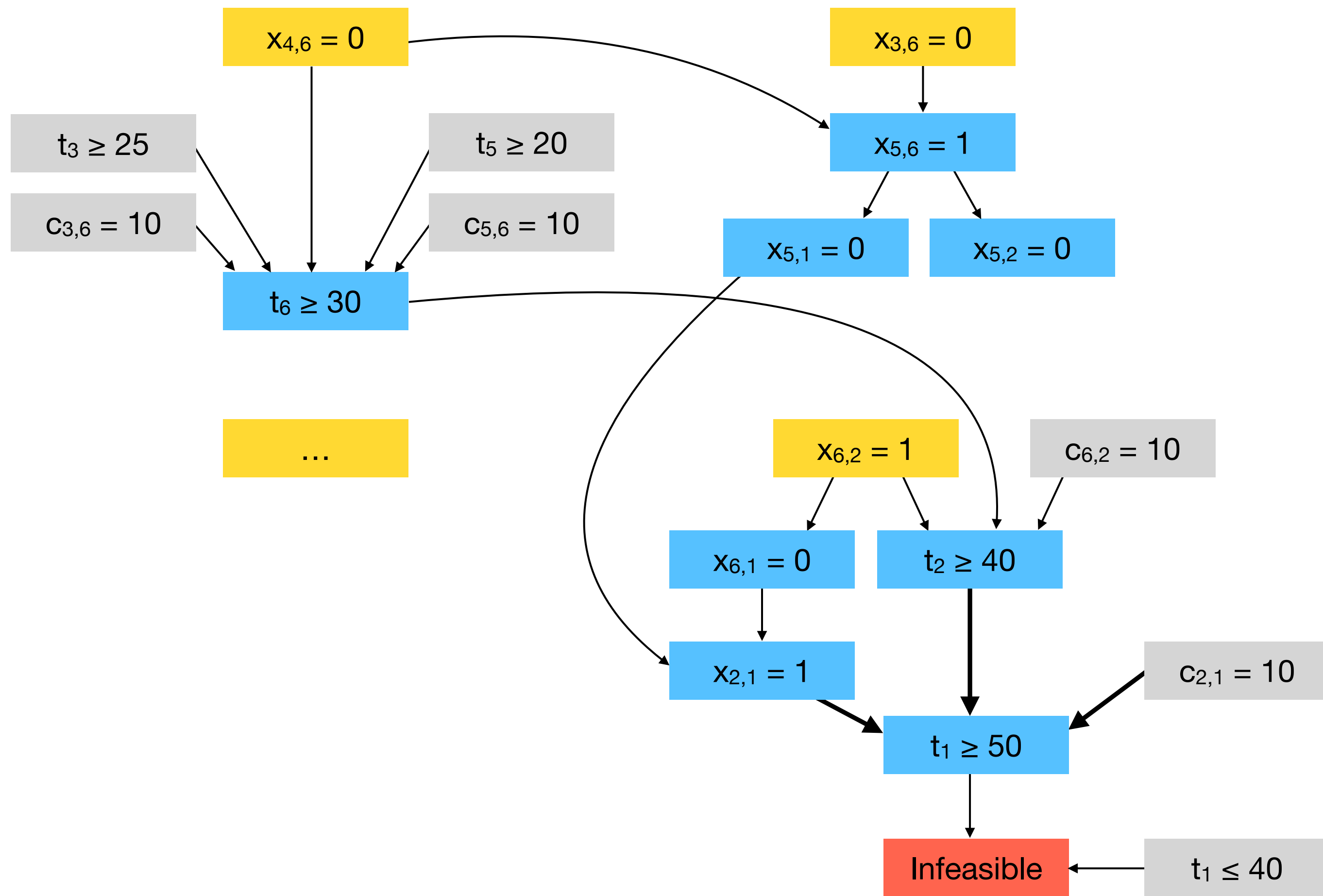
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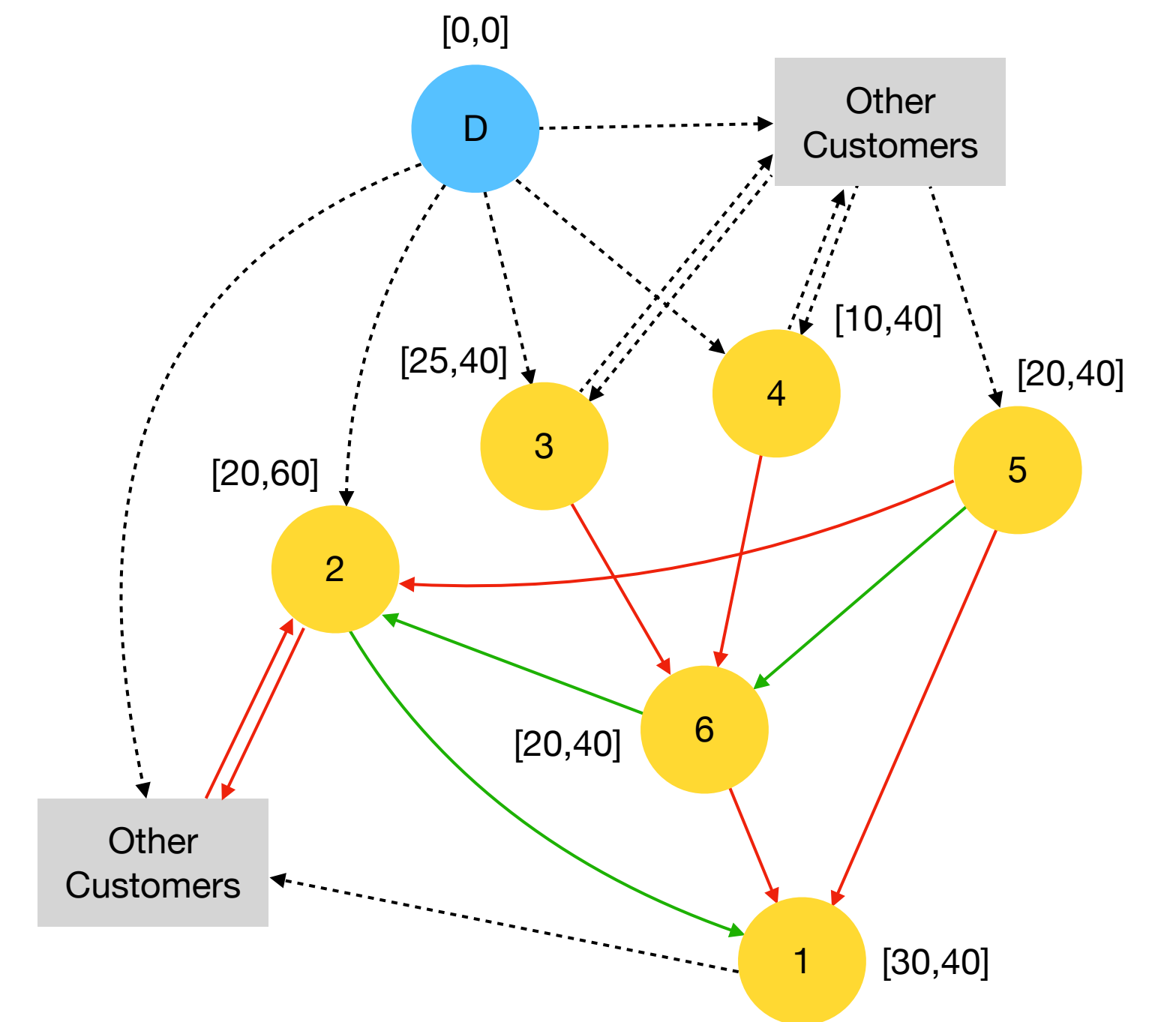
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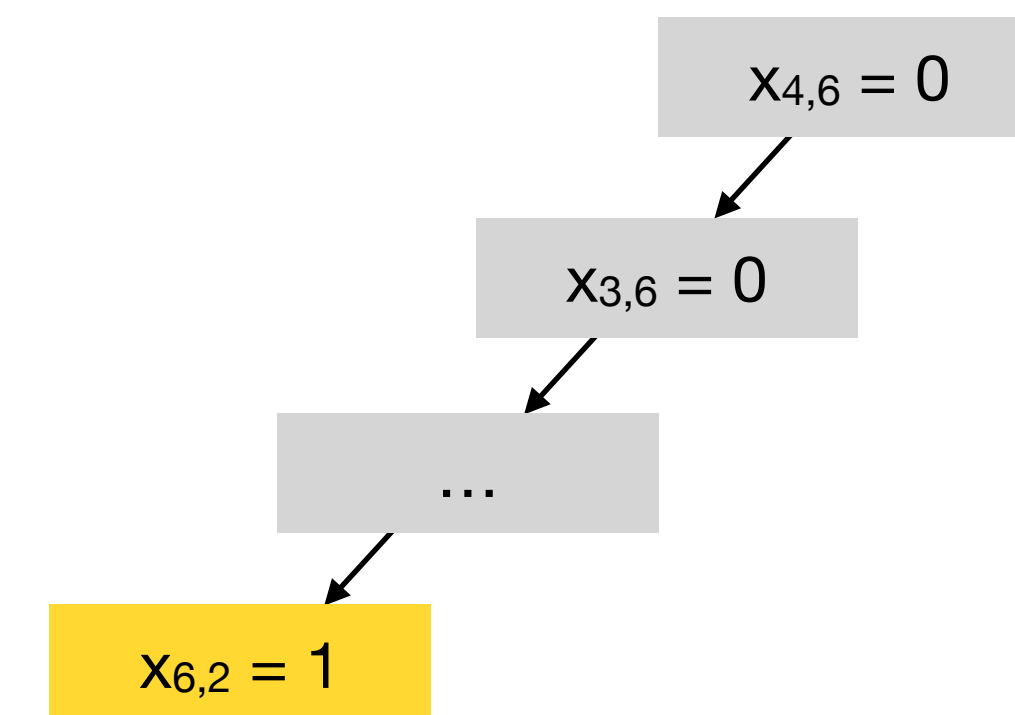
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## Network



## Branch-and-Bound Tree



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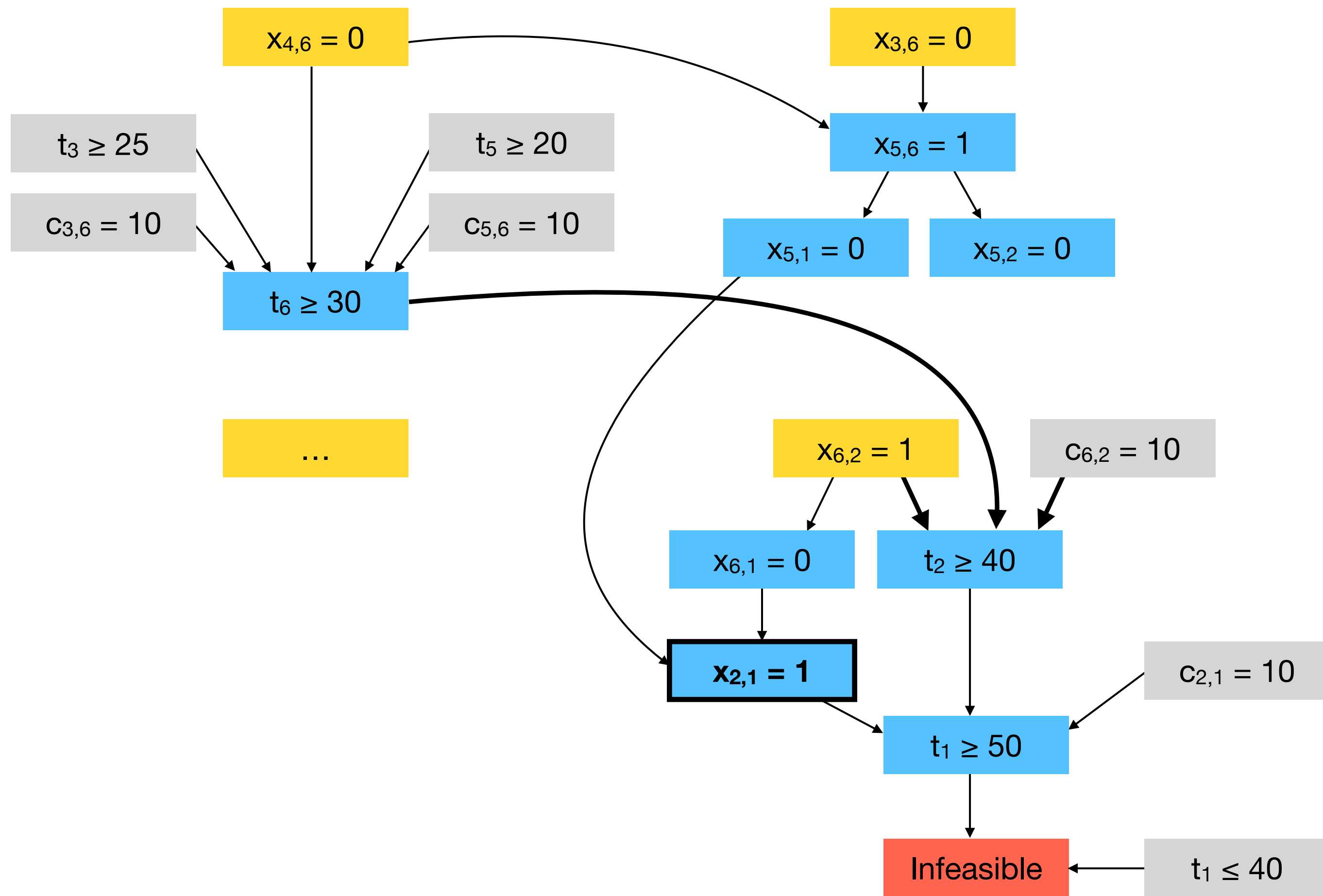
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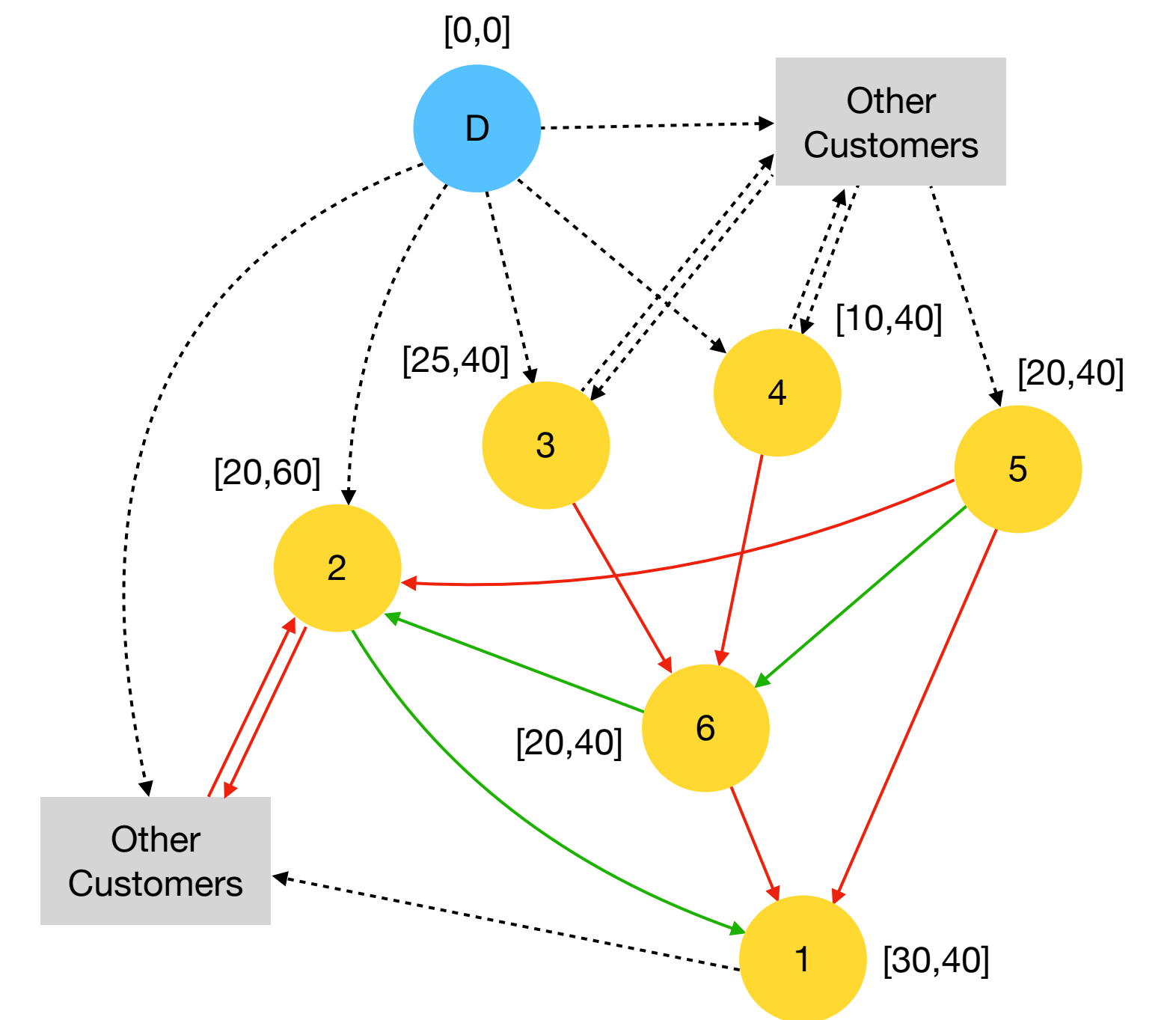
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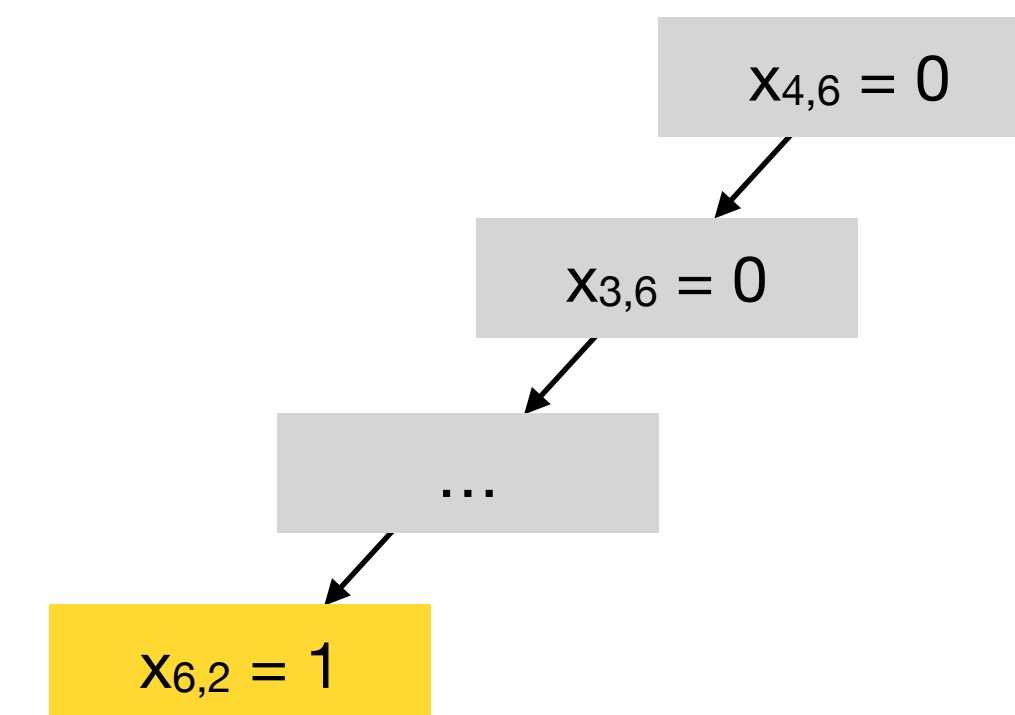
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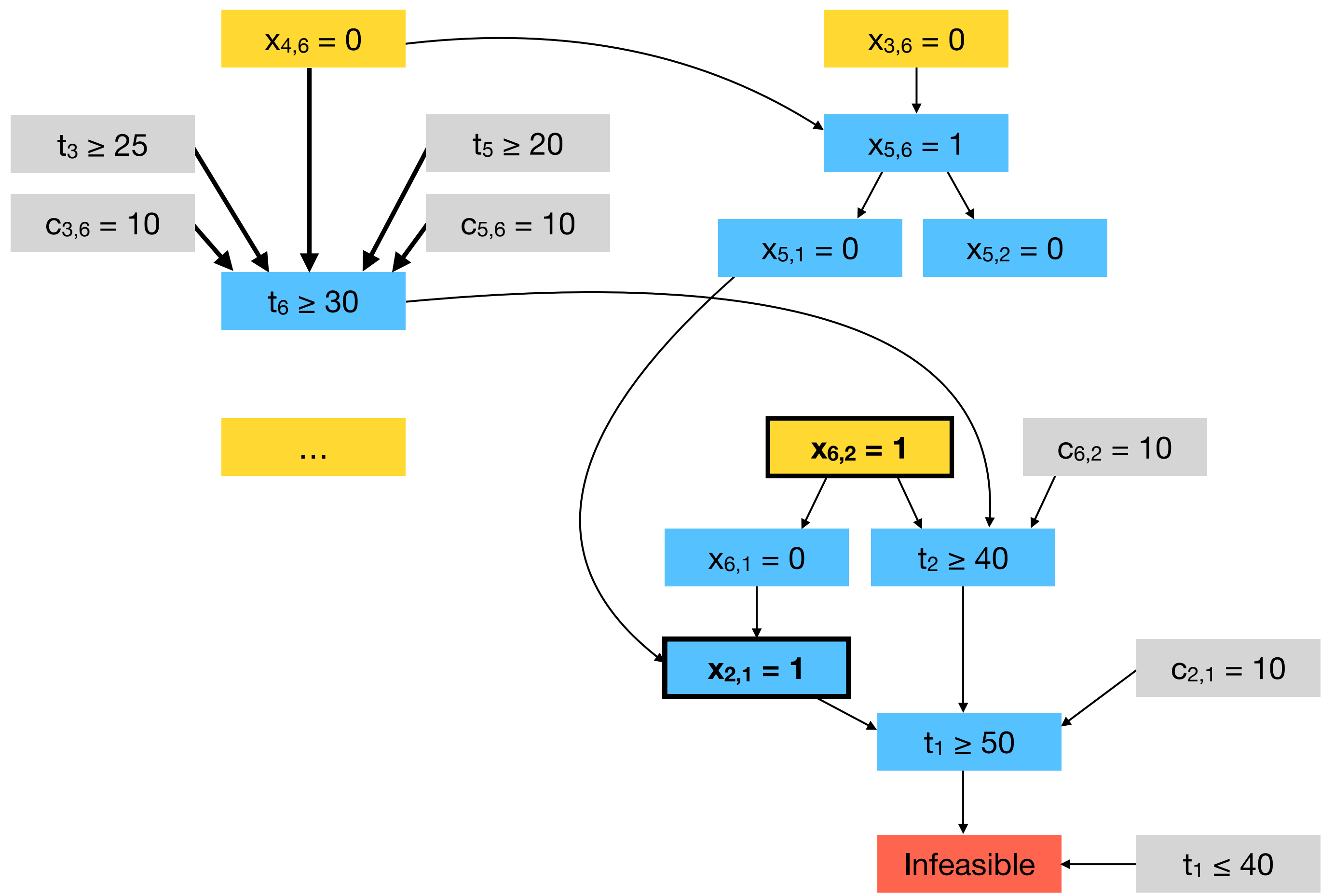


## Branch-and-Bound Tree

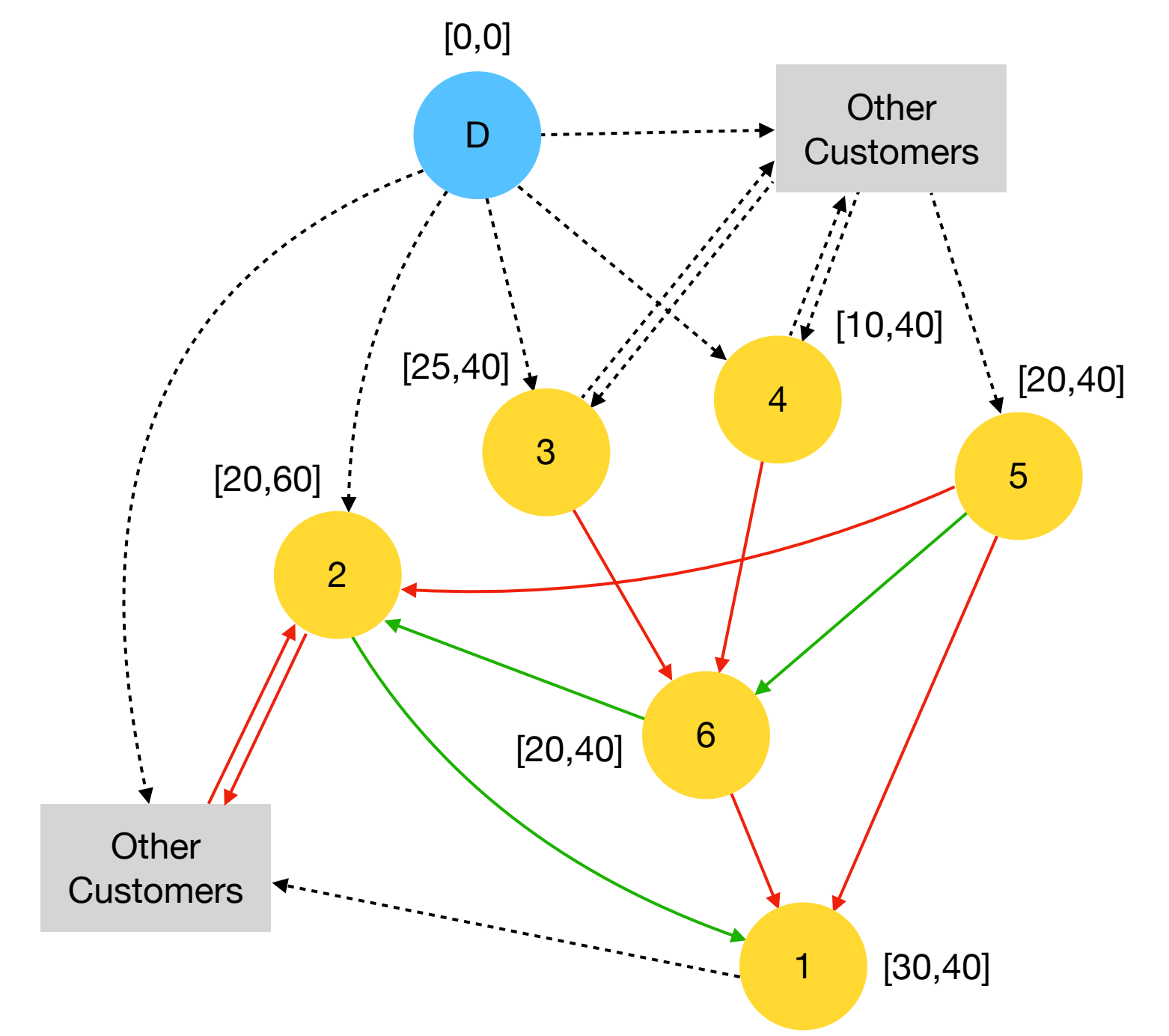


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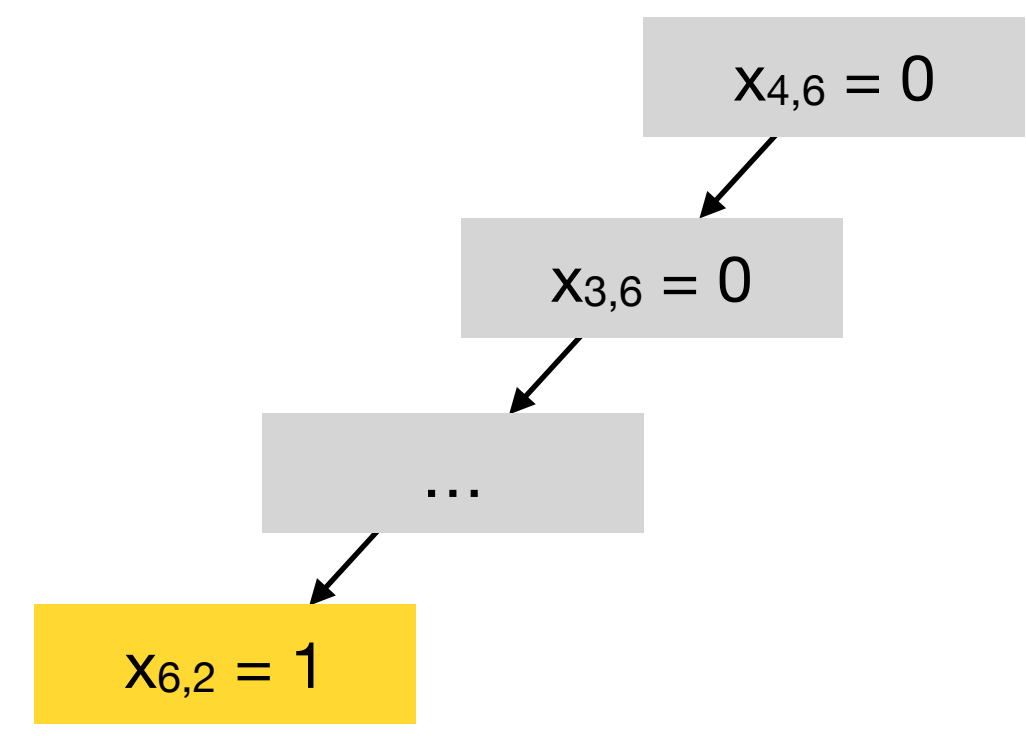
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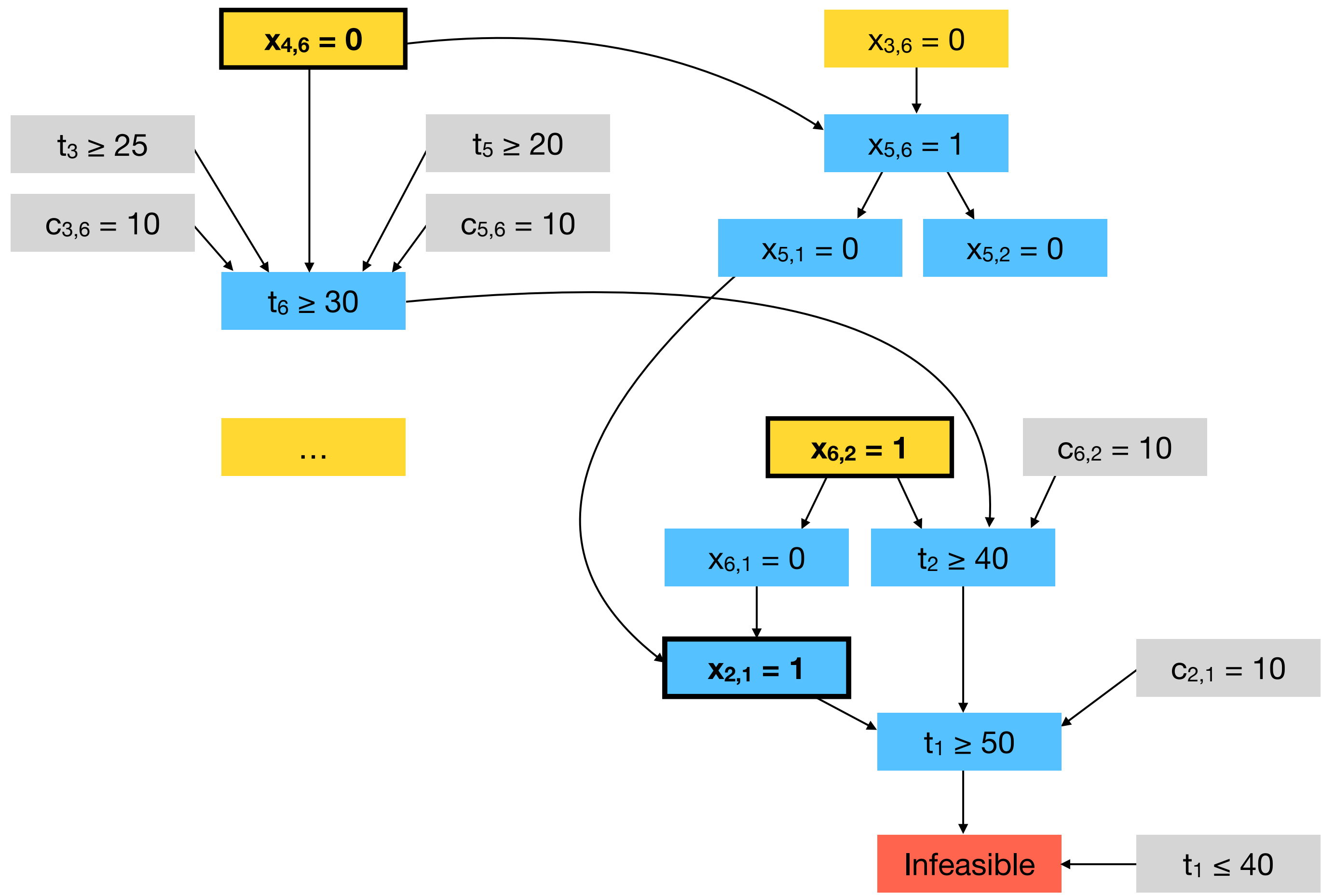


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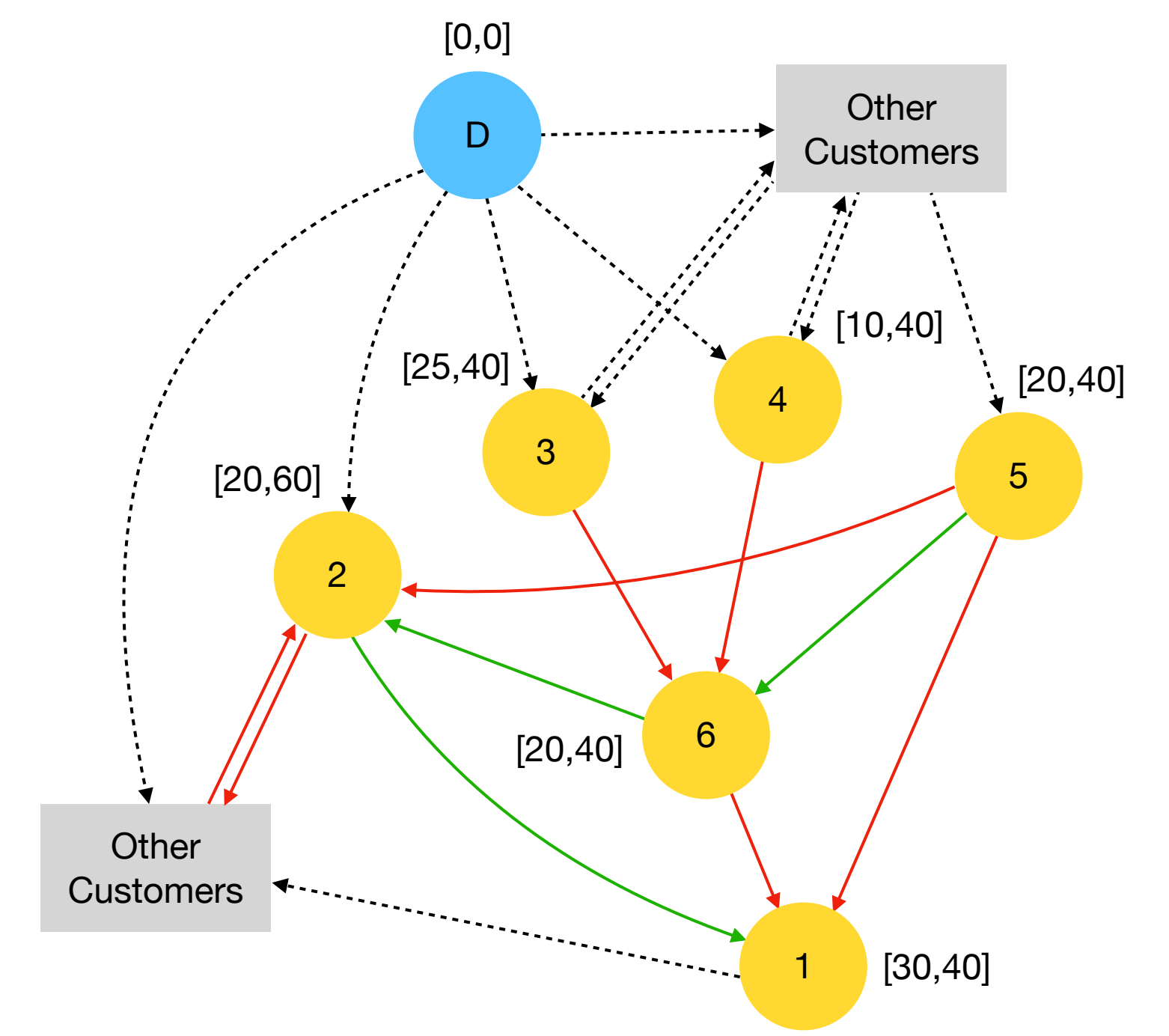


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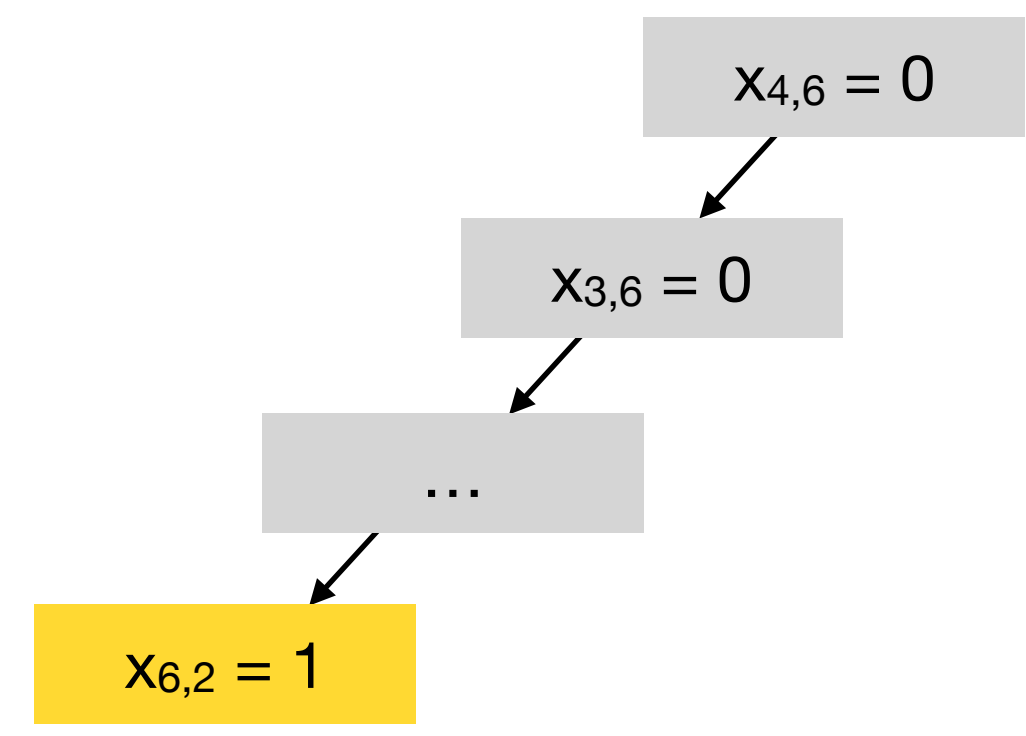
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# Network



# Branch-and-Bound Tree





## Implication Graph

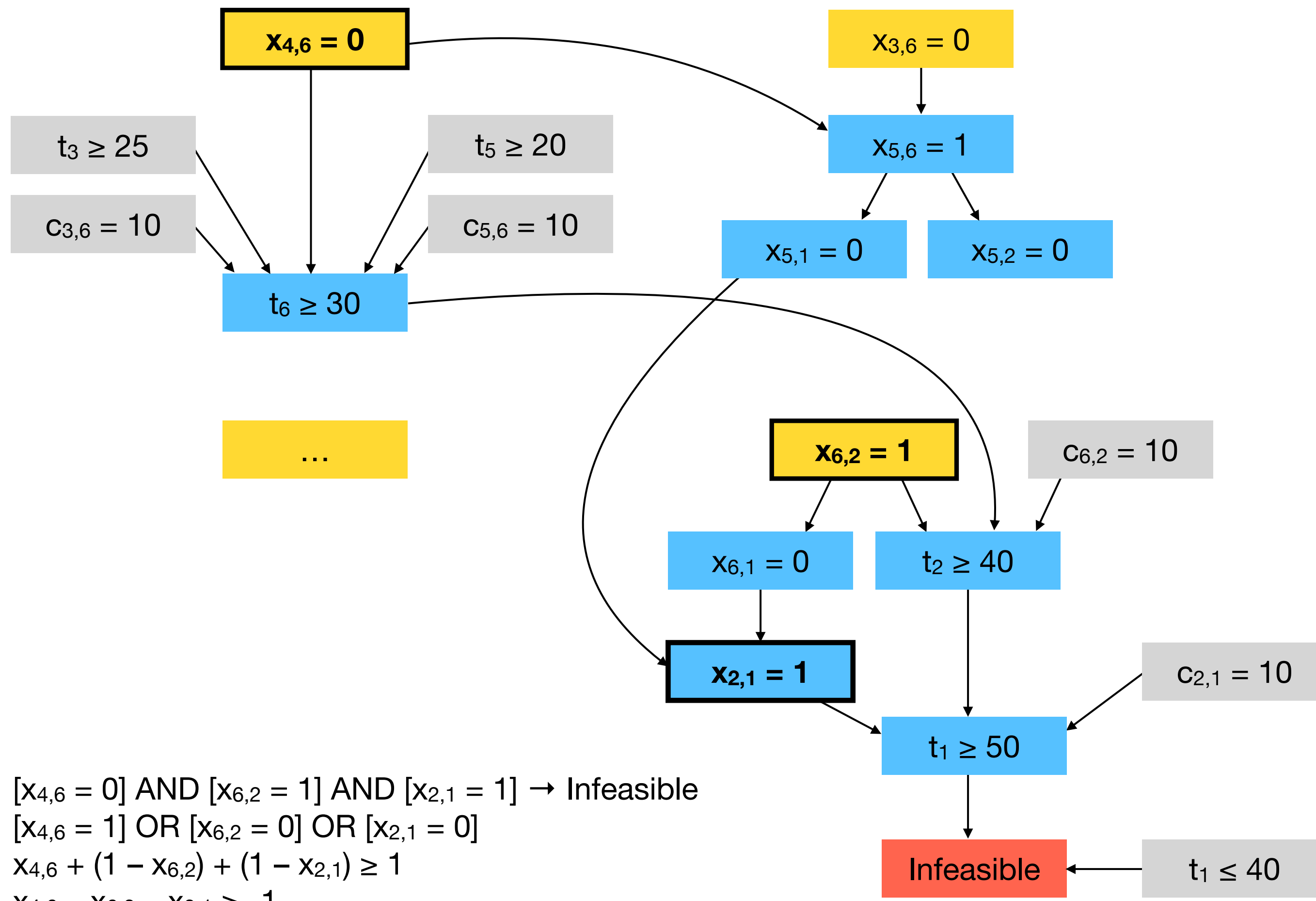
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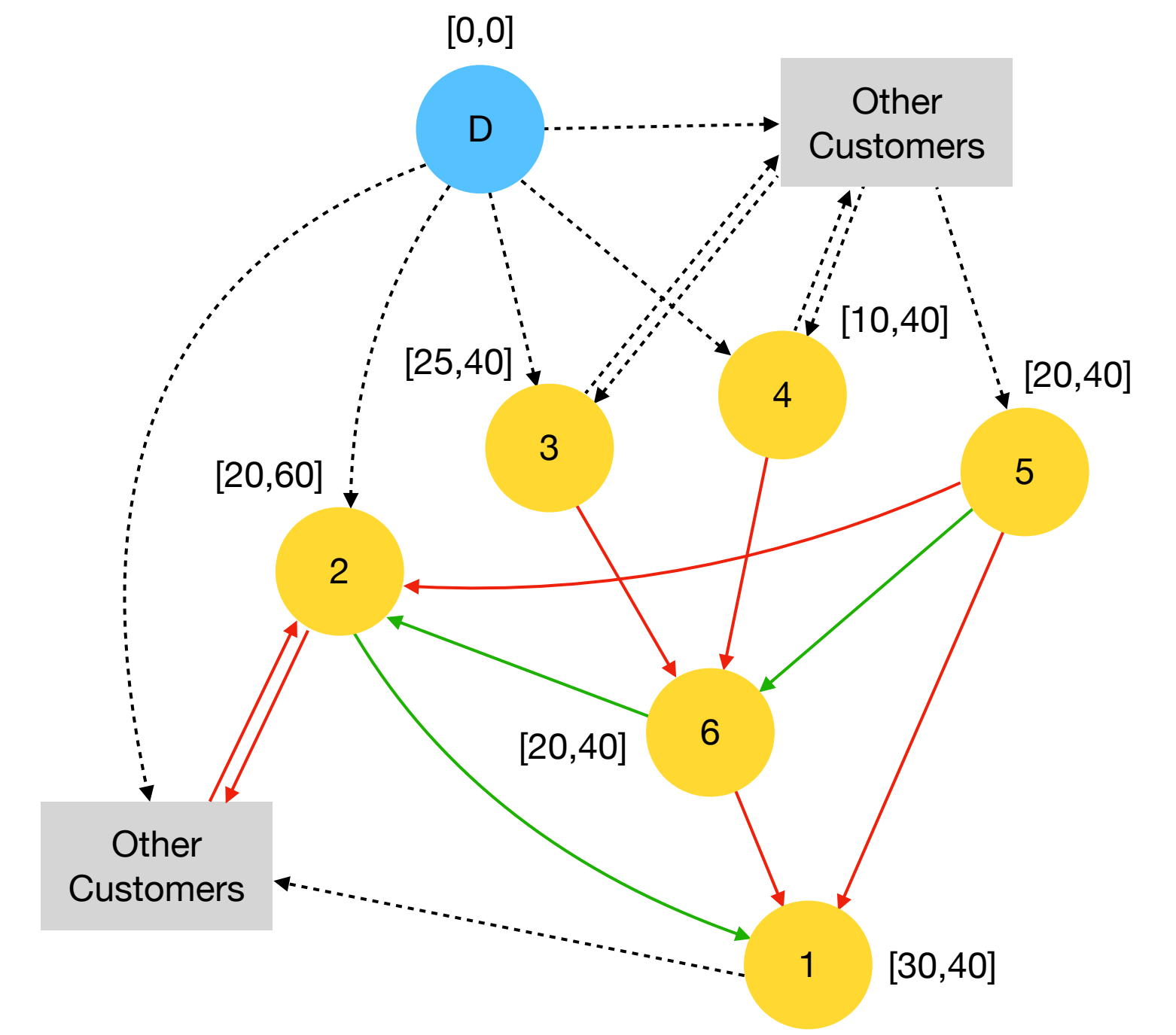
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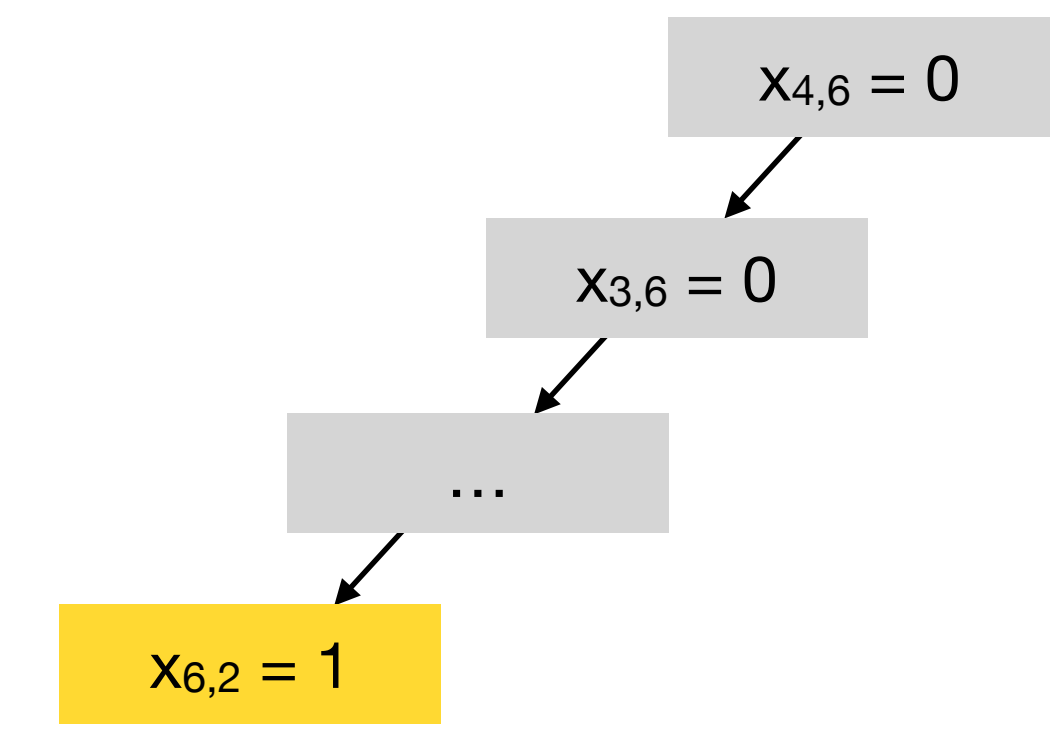


$[x_{4,6} = 0] \text{ AND } [x_{6,2} = 1] \text{ AND } [x_{2,1} = 1] \rightarrow \text{Infeasible}$   
 $[x_{4,6} = 1] \text{ OR } [x_{6,2} = 0] \text{ OR } [x_{2,1} = 0]$   
 $x_{4,6} + (1 - x_{6,2}) + (1 - x_{2,1}) \geq 1$   
 $x_{4,6} - x_{6,2} - x_{2,1} \geq -1$

## Network



## Branch-and-Bound Tree



# Caveat

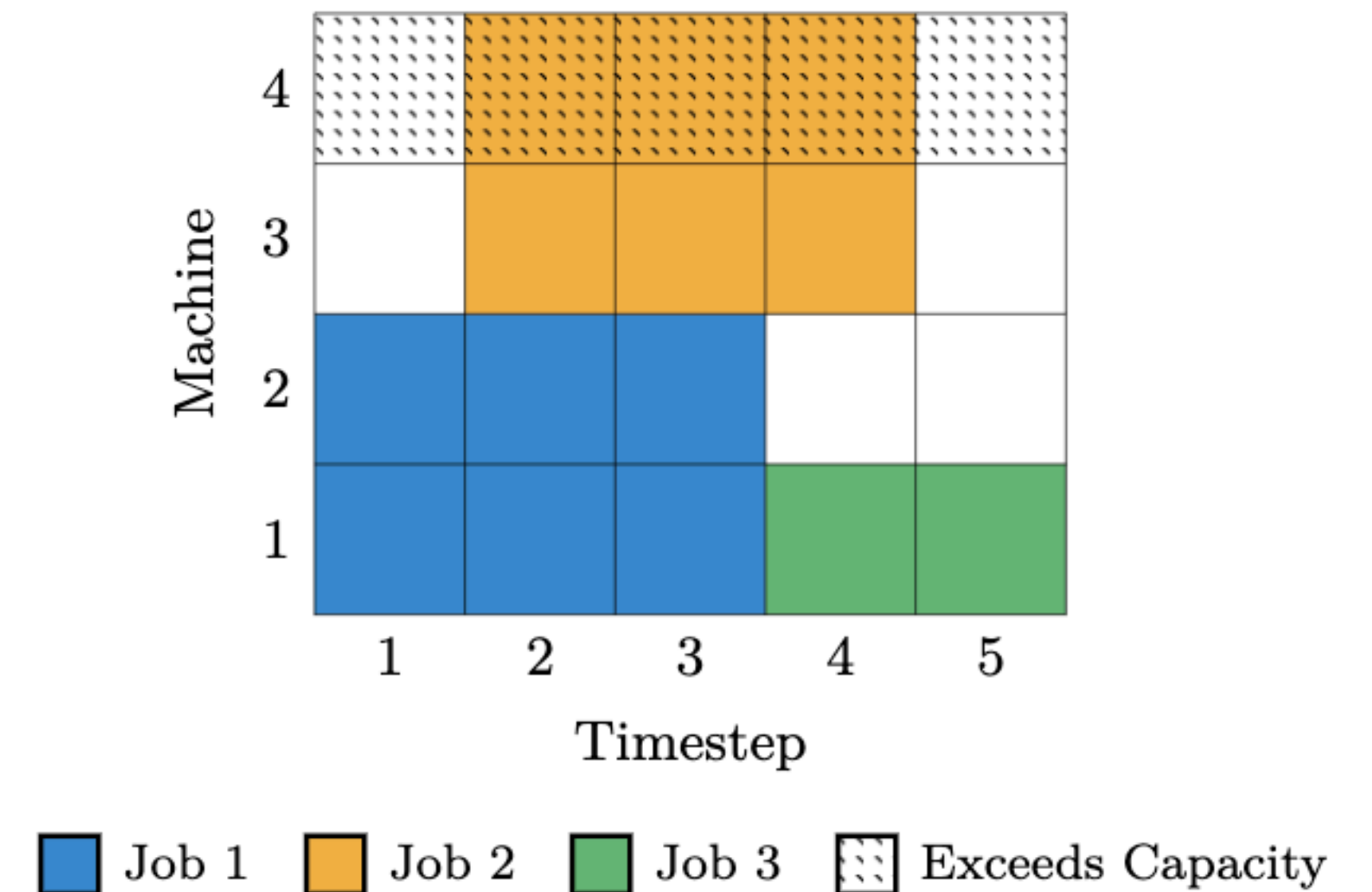
- In the example: trace the propagations backwards in the implication graph until all literals concern variables in the master problem.
- In practice: trace the implication graph backwards until (1) all literals concern variables in the master problem and (2) there is only one literal at the current depth of the branch-and-bound tree. Get a “first unique implication point” (1UIP) nogood. Experimental evidence from SAT suggests 1UIP nogoods perform better.

# Nutmeg

- A proof-of-concept automatic decomposition solver that implements the generic form of logic-based Benders decomposition.
- Calls SCIP for the MIP master problem and branch-and-bound.
- Calls Geas for the CP Benders subproblem and conflict analysis.
- Actually, just a bunch of SCIP plug-ins that glue the master problem and subproblem together.

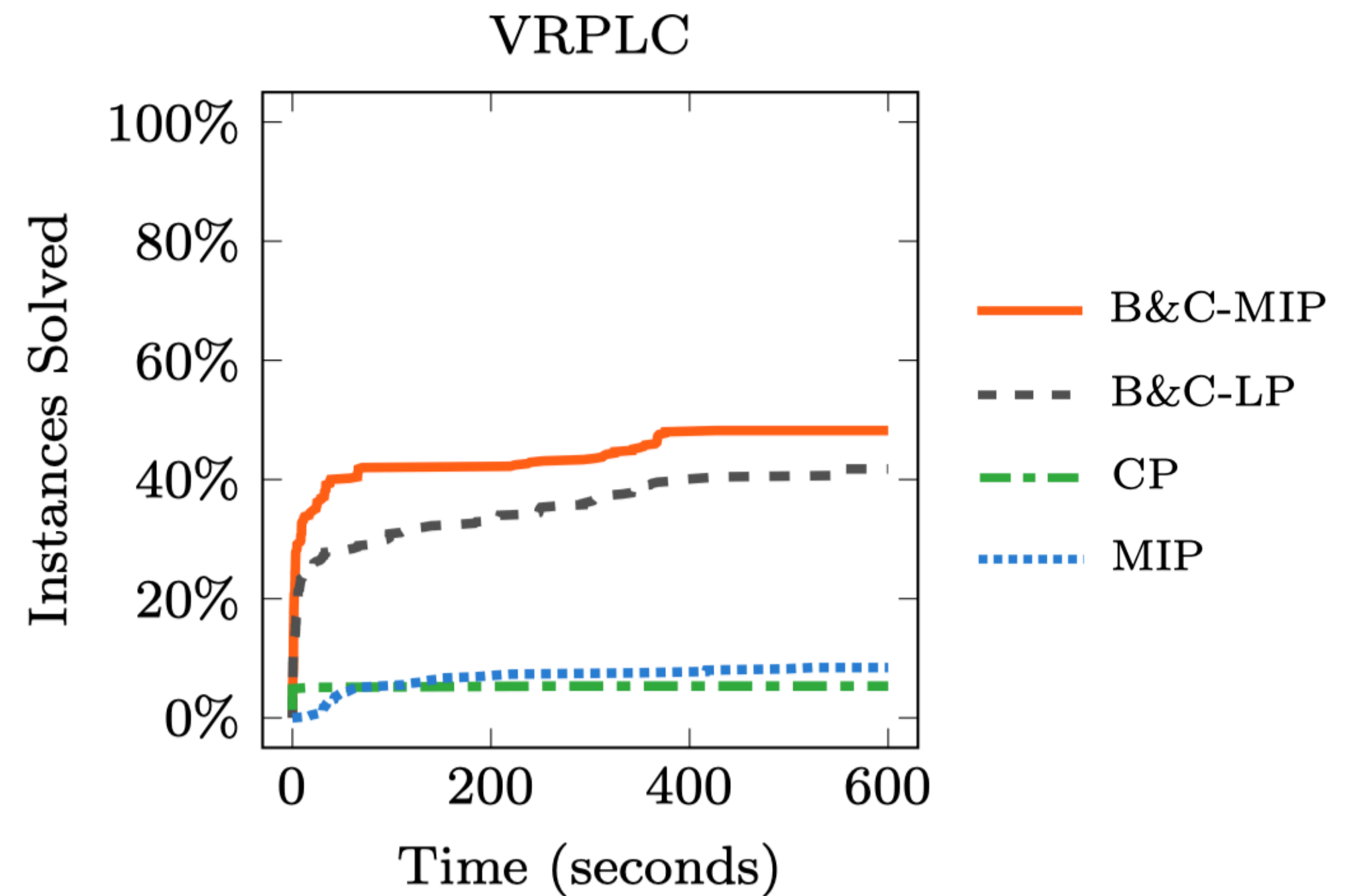
# Vehicle Routing Problem with Location Congestion

- Multiple customers have the same (x,y) coordinates. Deliveries to the same warehouse.
- Warehouses have a limited number of machines for unloading the vehicles.
- Vehicles must share the machines to unload.
- VRPLC has joint routing and scheduling combinatorial structure (a type of synchronization).



# Experimental Results

- MIP is good at network flow (TSP, VRP).
- CP is good at packing (RCPSP).
- Hybrid appears to be good at vehicle routing with scheduling.



# Experimental Results

- Nutmeg tested on a range of problems.
  - LBBD known to perform well on some problems (e.g., VRPLC).
  - LBBD performance unknown on majority of problems. No one has tried due to labor of deriving problem-specific cuts.
- Results confirm LBBD successes without manually deriving cuts.
- Mostly does not work. Problem still needs appropriate structure.
- Discovered one new problem suitable for LBBD.

# Key Points

- Logic-based Benders decomposition previously required problem-specific cuts.
- Otherwise, naive combinatorial Benders cuts work but are very weak.
- Conflict analysis can find tighter combinatorial Benders cuts (fewer variables).
- Recently implemented in an automatic decomposition solver named Nutmeg.
- Nutmeg works only on problems with appropriate structure.
- In VRP, “robust” cuts over arcs naturally translate to cuts over paths in branch-and-price.
- VRPs with synchronization become easy/easier. Generate the routes independently and then prevent a subset of arcs that violate the synchronization constraints. But no guarantee it’s fast.
- Super pre-alpha release at <https://github.com/ed-lam/nutmeg>.